

Shop Manual

PW170ES-6K

HYDRAULIC EXCAVATOR

SERIAL NUMBERS **PW170ES-6 -K30001** and up

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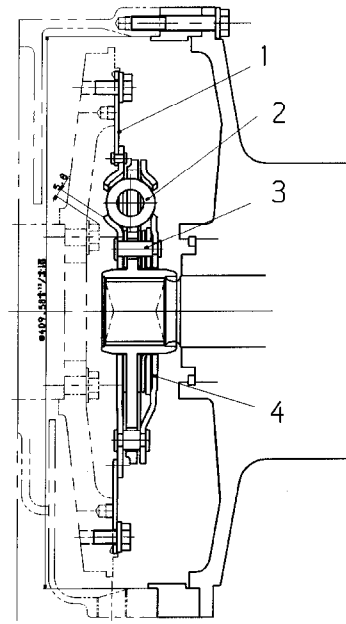
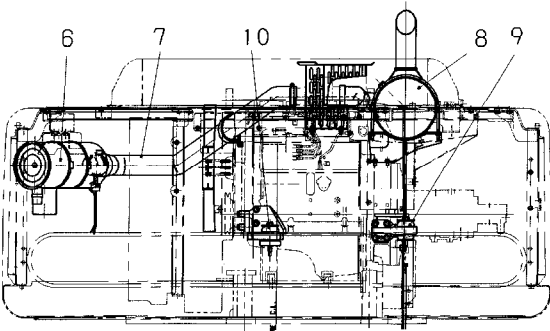
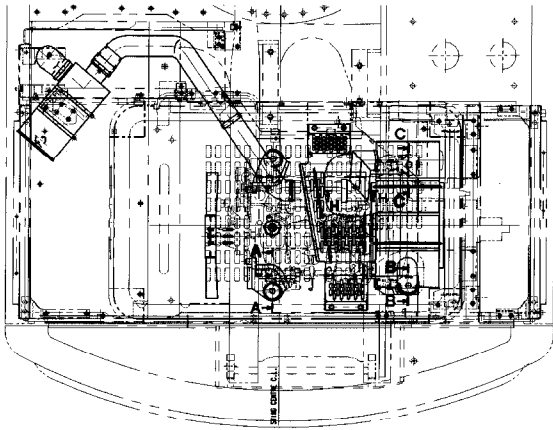
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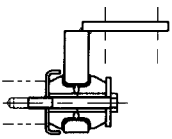
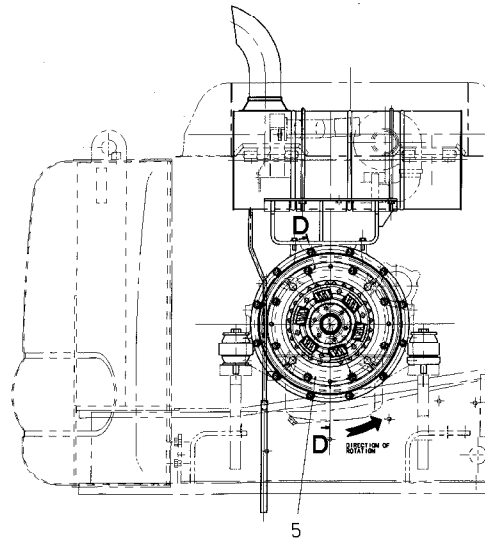
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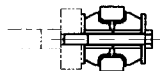
ENGINE RELATED PARTS



D-D



A-A



B-B



C-C



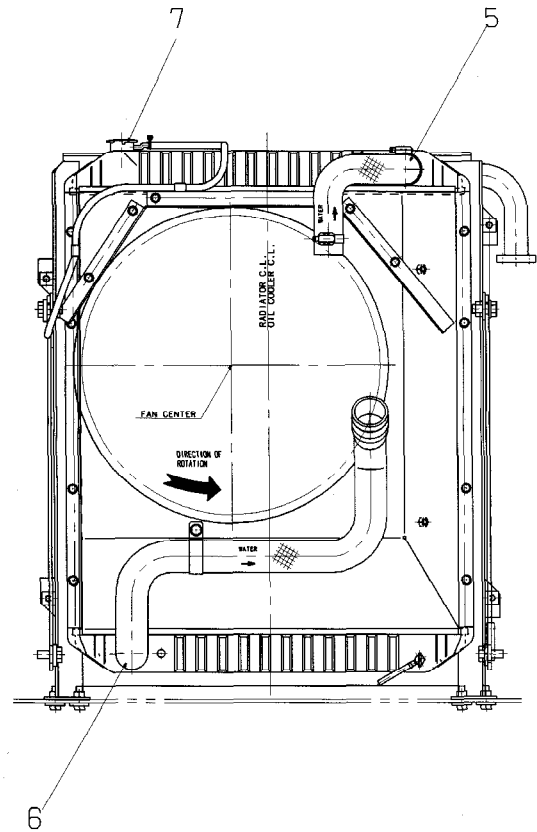
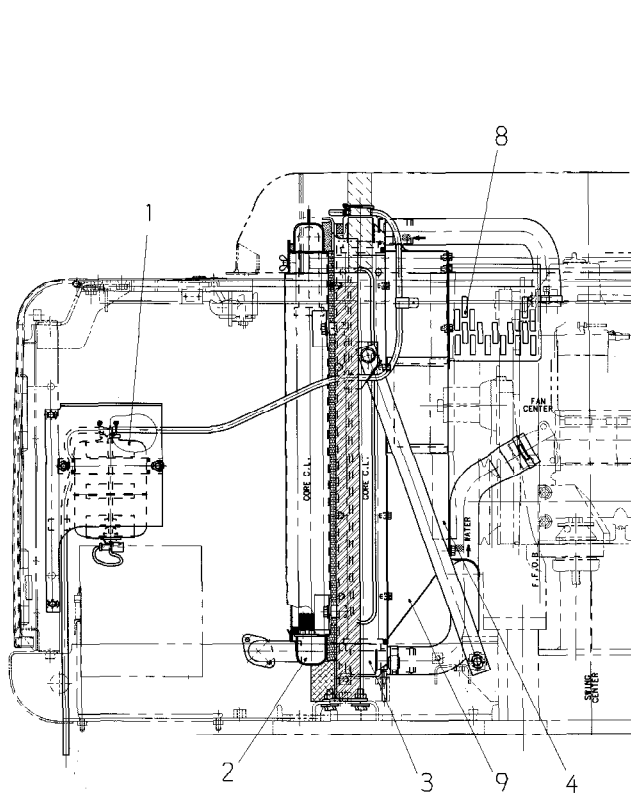
H-H

1. Drive plate
2. Torsion spring
3. Stopper pin
4. Friction plate
5. Damper assembly
6. Air cleaner
7. Intake connector
8. Muffler
9. Rear engine mount
10. Front engine mount

OUTLINE

- The damper assembly is a dry type.

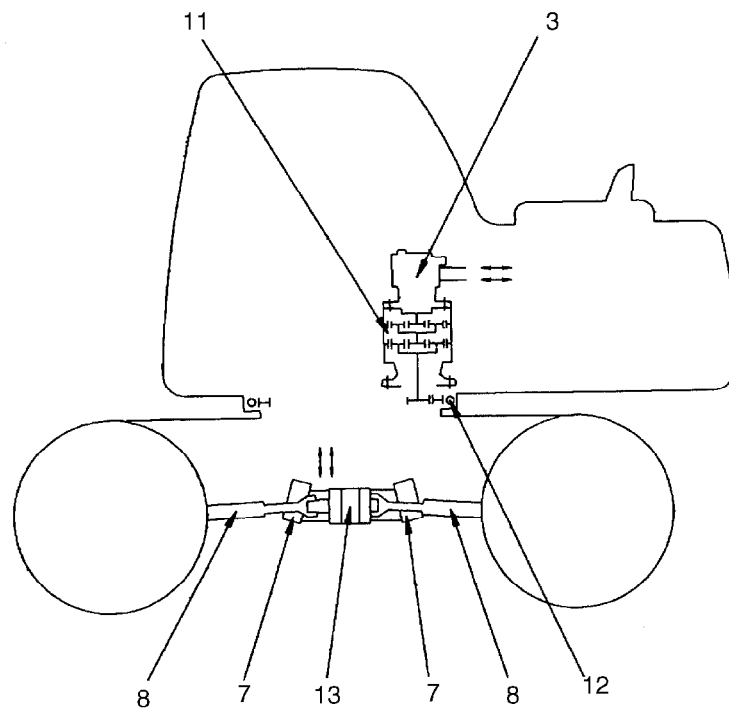
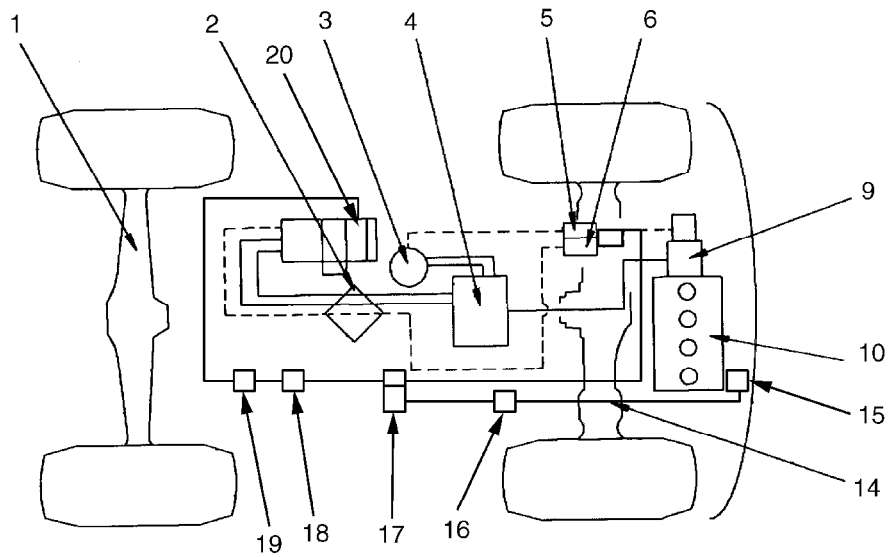
RADIATOR • OIL COOLER



1. Reservoir tank
2. Oil cooler
3. Radiator
4. Fan
5. Radiator inlet hose
6. Radiator outlet hose
7. Radiator cap
8. Net
9. Shroud

SPECIFICATIONS

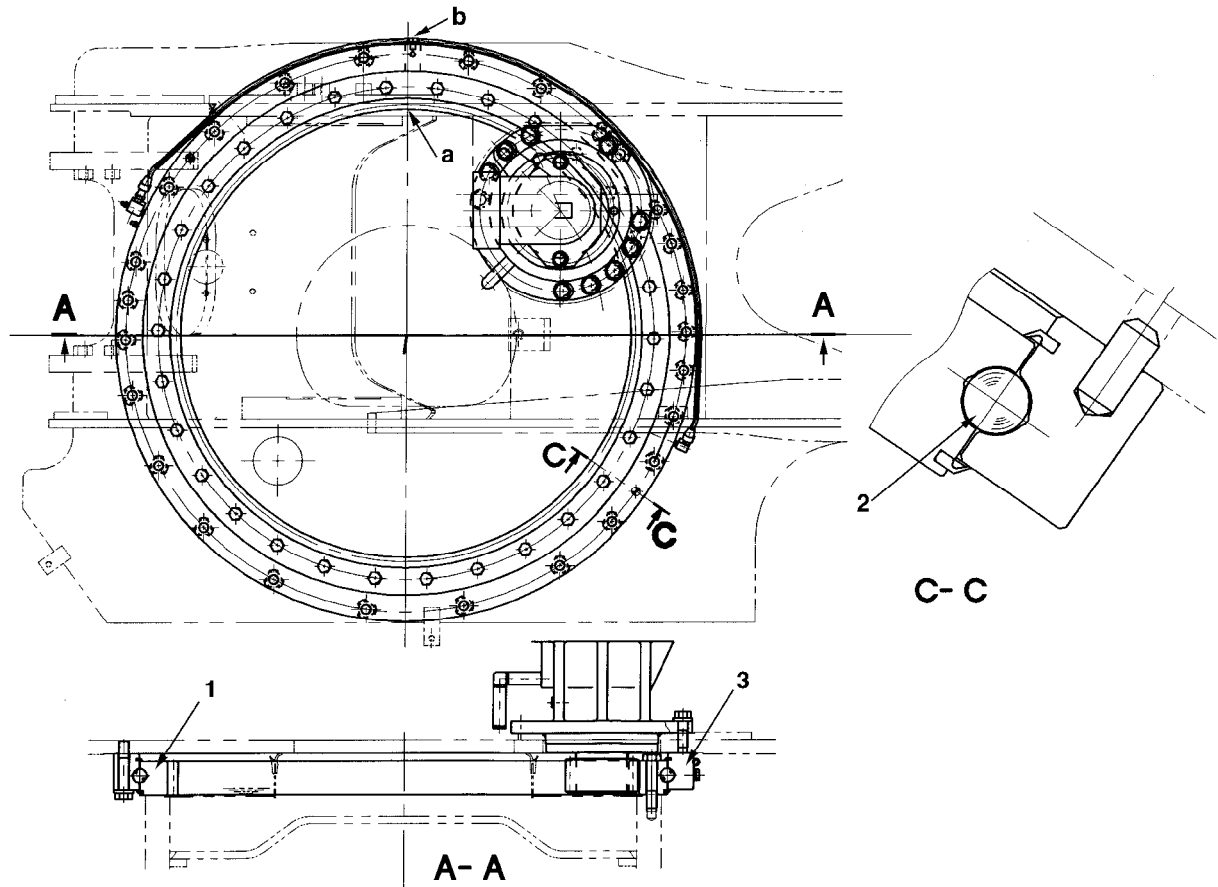
Radiator: CWX-4
 Oil cooler: SF-3



KW130P6001

- | | |
|--------------------------------|-----------------------------|
| 1. Front axle | 11. Swing machinery |
| 2. Center swivel joint | 12. Swing circle |
| 3. Swing motor | 13. Transmission |
| 4. Control valve | 14. Rear axle |
| 5. Swing brake solenoid valve | 15. Gear pump |
| 6. Travel speed solenoid valve | 16. Priority valve |
| 7. Travel motor | 17. Power brake valve |
| 8. Propshaft | 18. Pressure reducing valve |
| 9. Hydraulic pump | 19. Clutch control valve |
| 10. Engine | 20. Clutch |

SWING CIRCLE



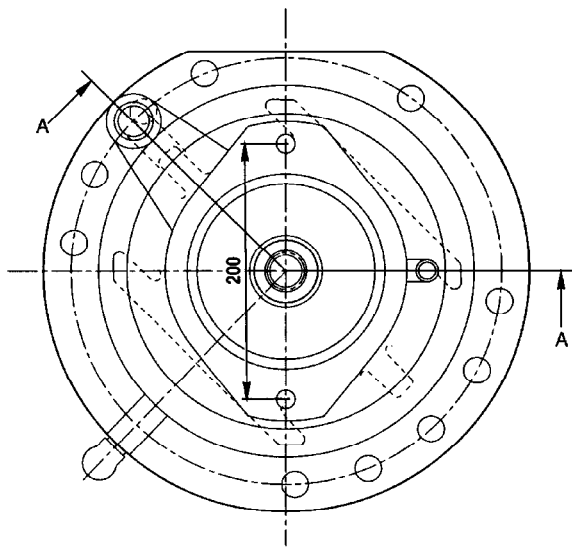
1. Swing circle inner race (No. of teeth: 94)
 2. Ball
 3. Swing circle outer race
- a. Inner race soft zone **S** position
 b. Outer race soft zone **S** position

SPECIFICATIONS

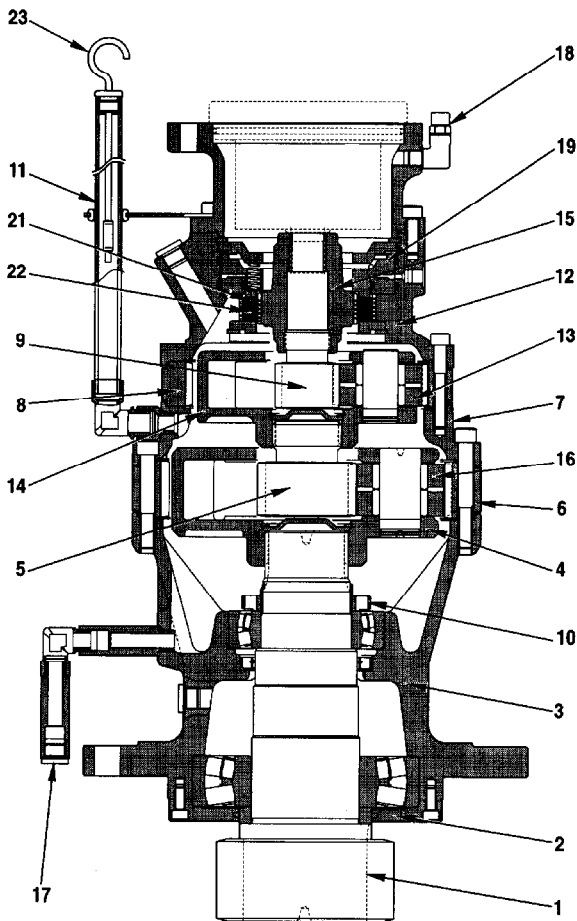
reduction ratio: $\frac{94}{12} = 7.833$

amount of grease: $8/(G2-LI)$

SWING MACHINERY



1. Swing pinion (No. of teeth: 12)
2. Cover
3. Case
4. No. 2 of planetary carrier
5. No. 2 sun gear (No. of teeth: 24)
6. No. 2 ring gear (No. of teeth: 78)
7. Case
8. No. 1 ring gear (No. of teeth: 78)
9. No. 1 sun gear (No. of teeth: 18)
10. Retainer
11. Oil level gauge
12. Cover
13. No. 1 planetary gear (No. of teeth: 29)
14. No. 1 planetary carrier
15. Coupling
16. No. 2 planetary gear (No. of teeth: 26)
17. Drain plug
18. Breather
19. Parking brake piston
20. Parking brake spring
21. Parking brake disc
22. Parking brake plate
23. Gauge rod



SPECIFICATIONS

$$\text{reduction ratio: } \frac{24+78}{24} \times \frac{18+78}{18} = 22.667$$

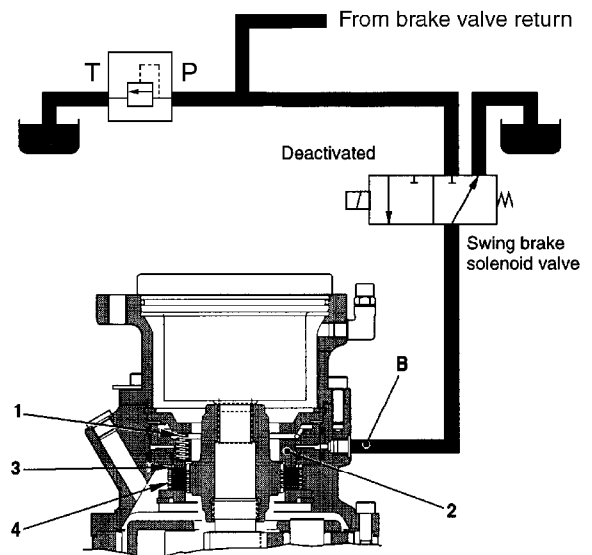
SWING HOLDING BRAKE

OPERATION

1) When swing brake solenoid valve is deactivated

When the swing brake solenoid is deactivated, the pressurized oil from the PPC pressure reducing valve is shut off and port **B** is connected to the tank circuit.

Because of this, brake piston (2) is pushed down in the direction of the arrow by brake spring (1), so disc (3) and plate (4) are pushed together and the brake is applied.

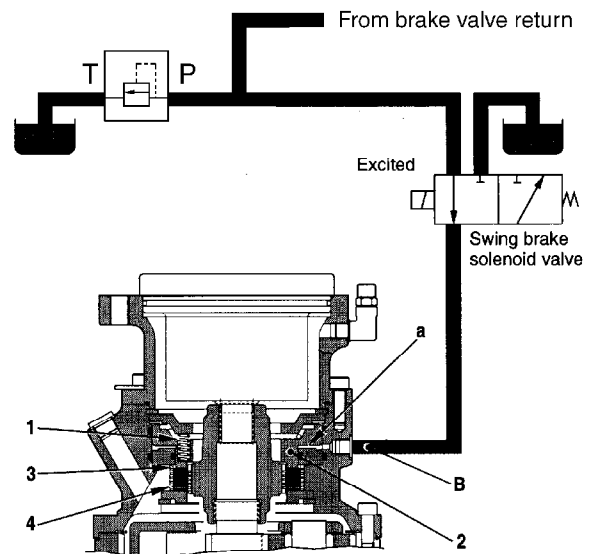


2) When swing brake solenoid valve is excited

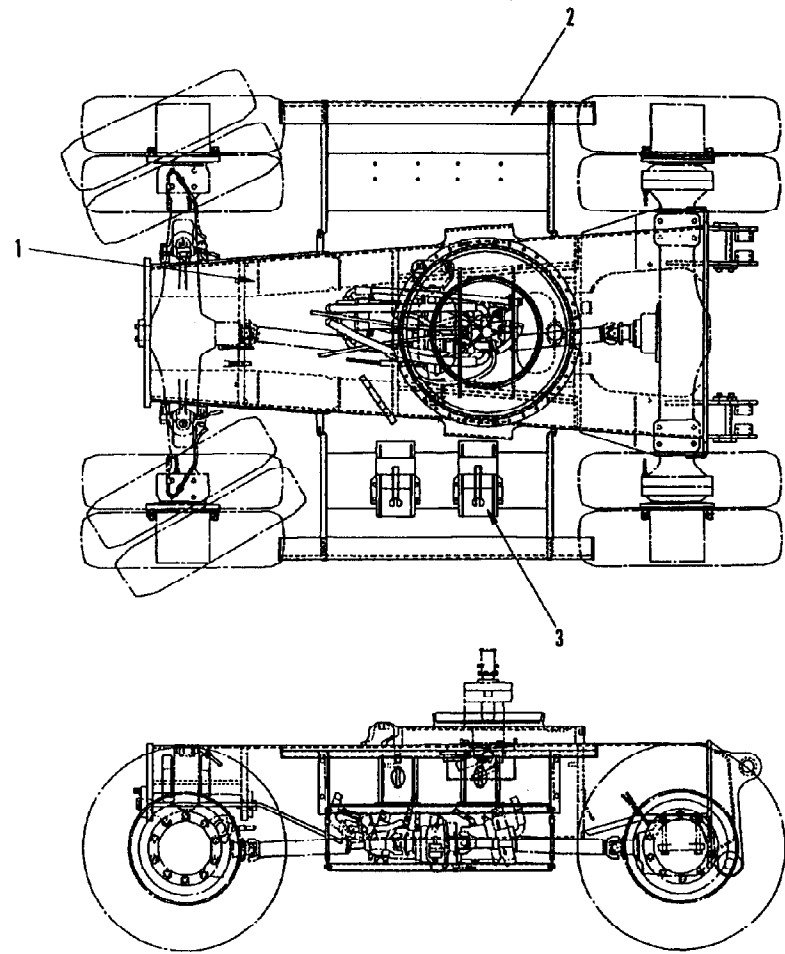
When the swing solenoid valve is excited, the valve is switched, and the pressurized oil from the PPC pressure reducing valve enters port **B** and flows to brake chamber "a".

The pressurized oil entering chamber "a" overcomes the force of brake spring (1), and brake piston (2) is pushed up in the direction of the arrow. Because of this, disc (3) and plate (4) separate, and the brake is released.

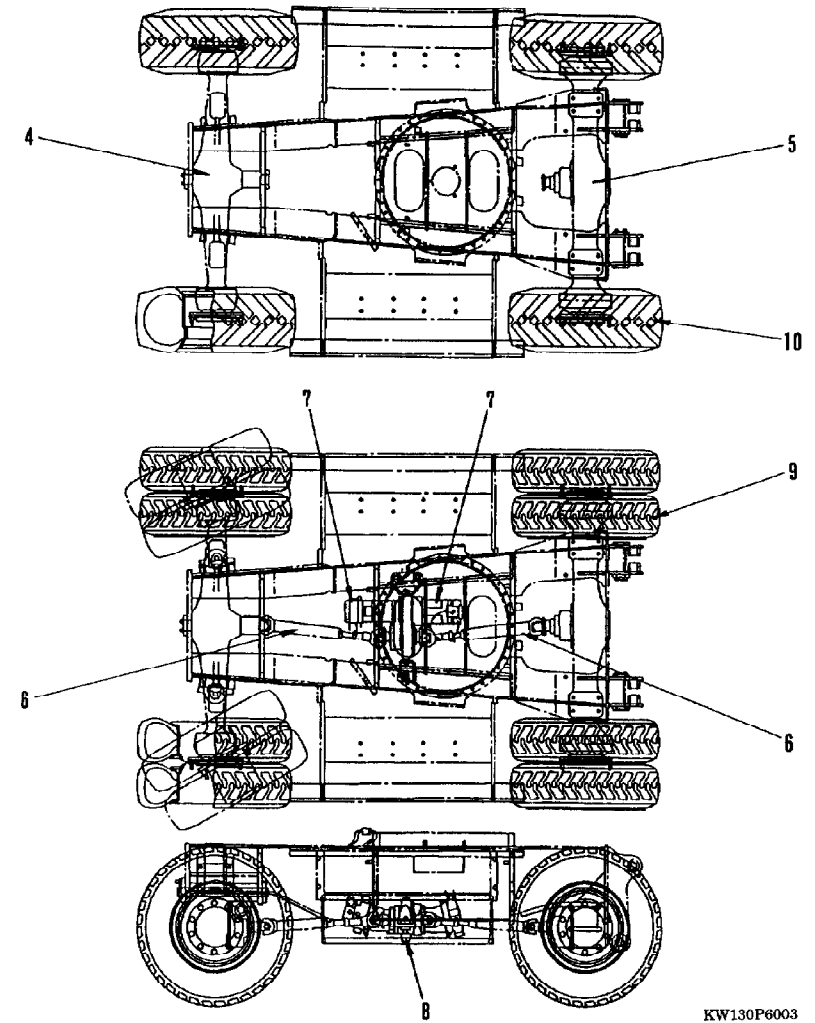
1. Brake spring
2. Brake piston
3. Disc
4. Plate



UNDERCARRIAGE



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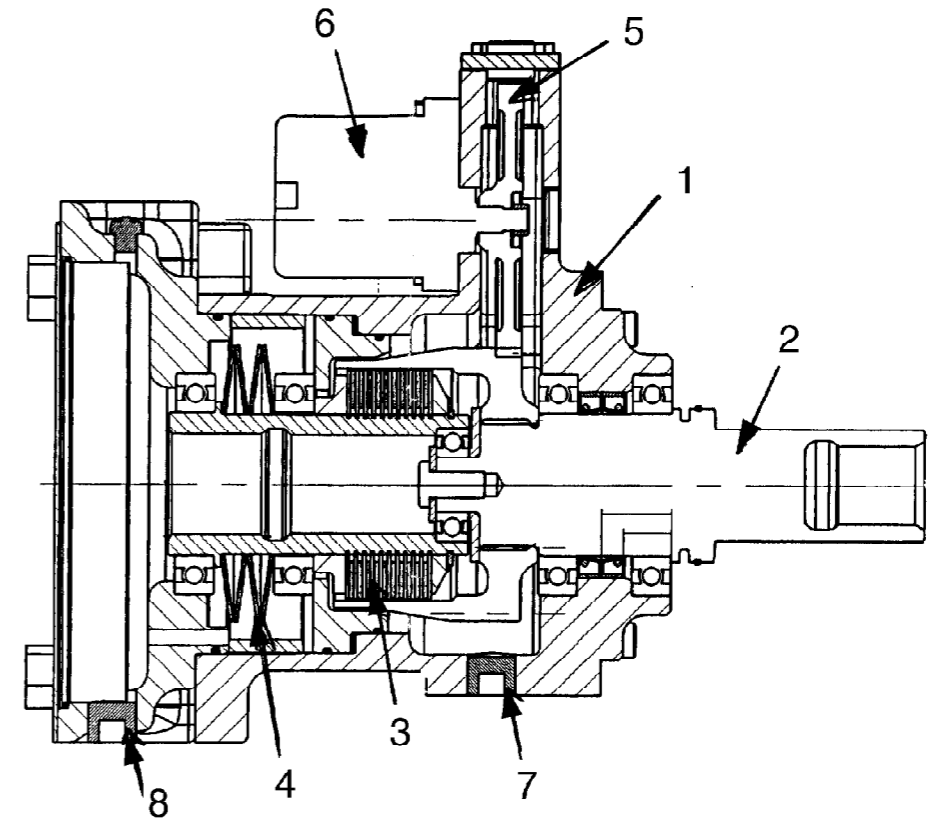
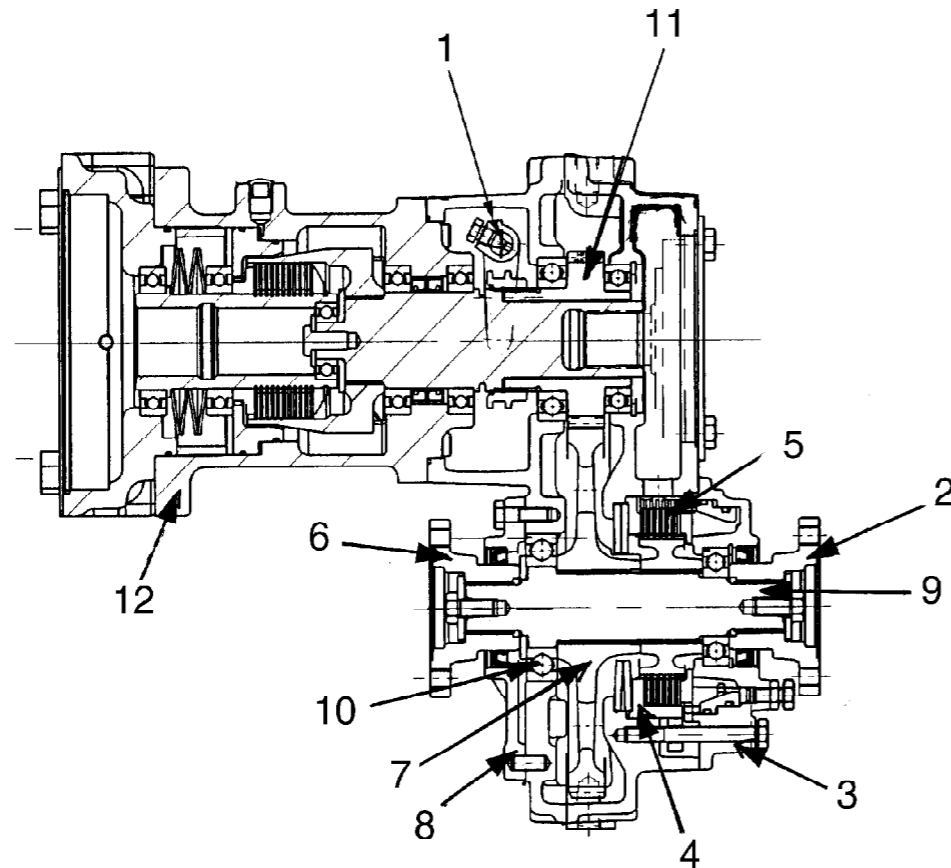


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- | | |
|------------------------------------|------------------------|
| 1. Undercarriage | 6. Propshaft |
| 2. Step | 7. Travel motor |
| 3. Wheel chock | 8. Transmission |
| 4. Front oscillating steering axle | 9. Double wheel ass'y |
| 5. Rear axle | 10. Single wheel ass'y |

TRANSMISSION

CLUTCH ASS'Y



- 1. Screw-fork to shaft
- 2. Flange
- 3. Brake cylinder
- 4. Brake drum
- 5. Friction disk
- 6. Flange

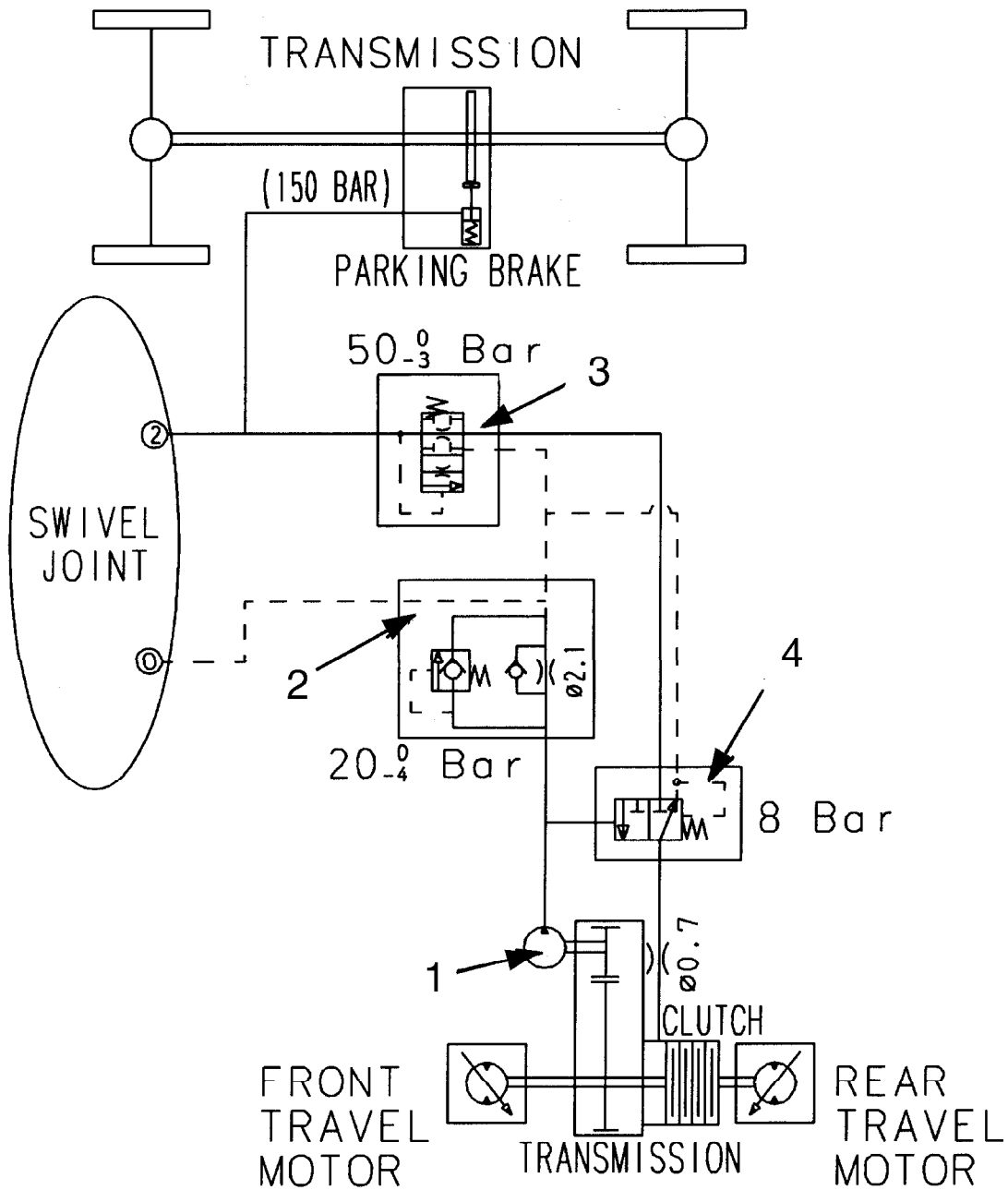
- 7. Gear
- 8. Cover
- 9. Output shaft
- 10. Bearing
- 11. Gear
- 12. Clutch ass'y

- 1. Casing
- 2. Drive shaft
- 3. Friction plates
- 4. Spring discs
- 5. Gear
- 6. Clutch control gear pump

- 7. Plug
- 8. Plug

CLUTCH CONTROL CIRCUIT

STRUCTURE



1. Clutch control pump
2. Pressure relief valve ass'y
3. Pressure reducing valve
4. Clutch control valve

FUNCTION

The clutch is a device which automatically disengages the drive between the 200 cc (rear) travel motor and the transmission. This occurs when the machine is accelerating and the disengagement occurs at 11 Kph. The transmission system becomes more efficient (by reducing losses caused by the unnecessary rotation of the rear travel motor) providing better acceleration and enabling a maximum speed of 30 Kph.

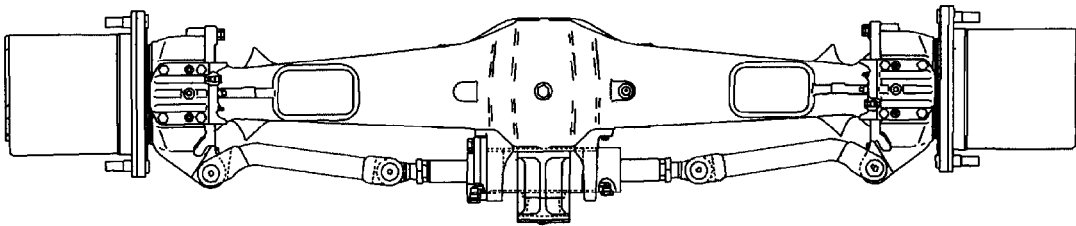
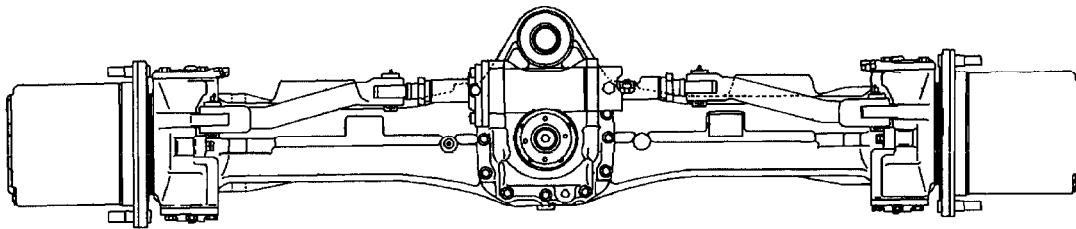
When the machine decelerates from a high speed the clutch will re-engage automatically at 9 Kph and will remain engaged until the speed is increased above 11 Kph again.

AXLE

OUTLINE

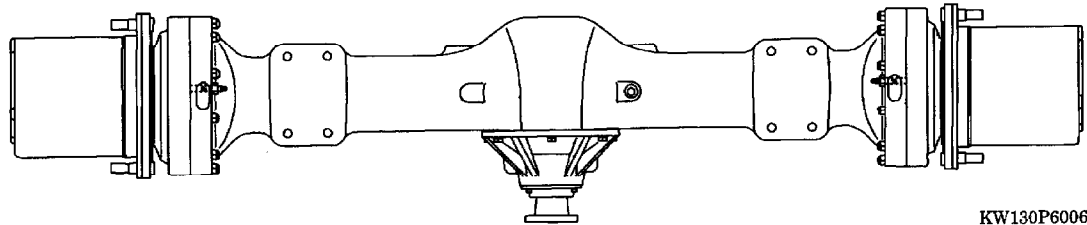
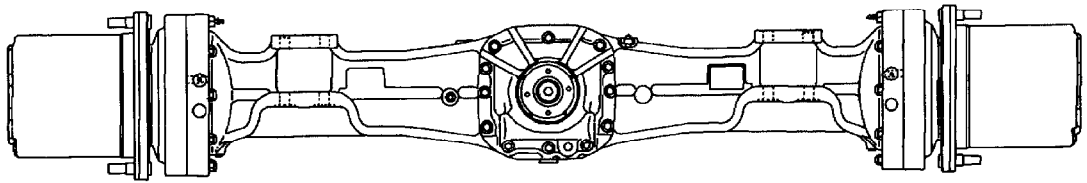
- Each axle consists of an axle housing supporting the chassis weight, a differential set in the axle housing, a final drive, and a brake provided at each end.
- A trunnion-type axle shaft with a king pin at the final drive end is used to enable the direction of travel of the machine to be changed.

FRONT AXLE



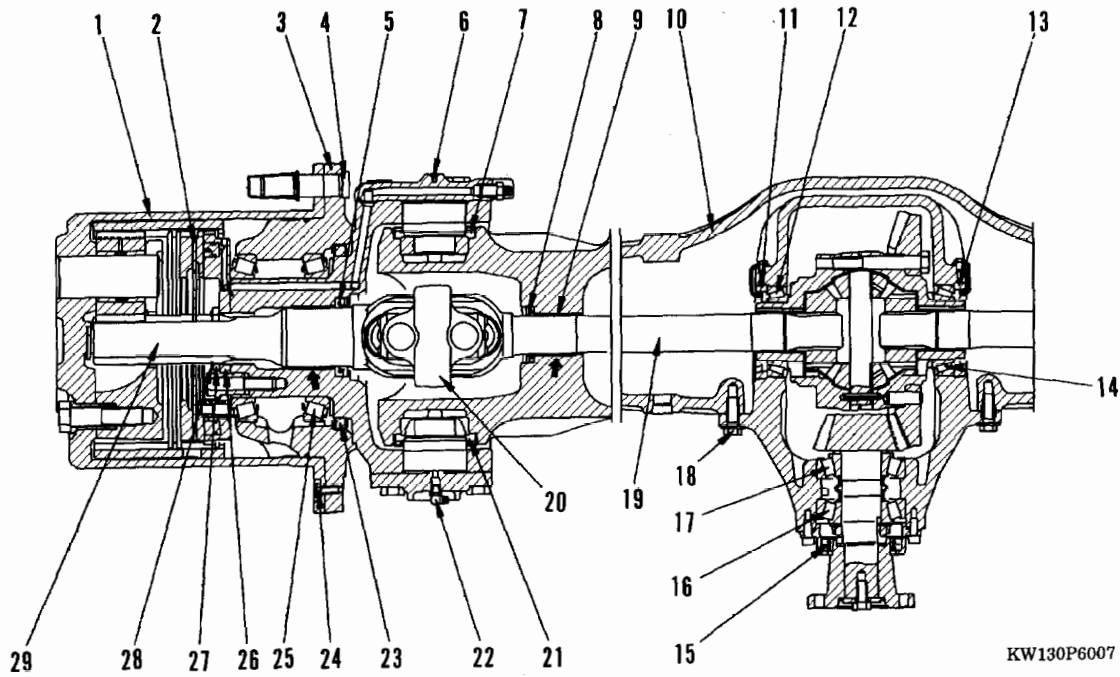
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REAR AXLE



KW130P6006

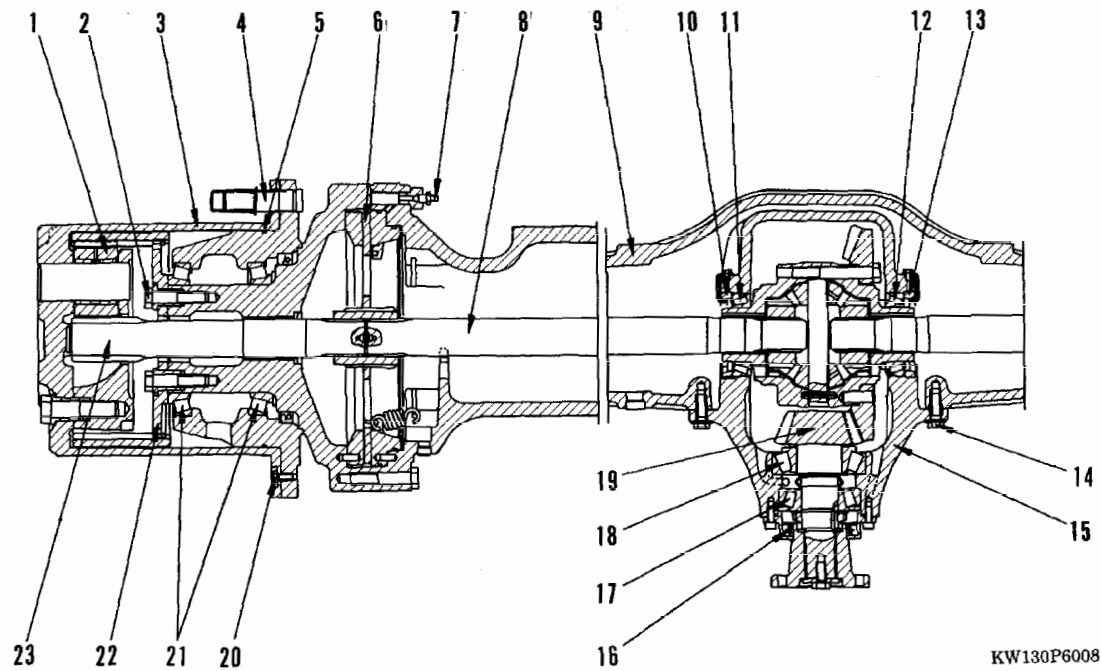
FRONT AXLE



Axle reduction ratio = 17, 73:1

- | | |
|----------------------|-------------------------|
| 1. Planetary carrier | 16. Roller bearing |
| 2. Washer | 17. Roller bearing |
| 3. Brake drum | 18. Hexagon head screw |
| 4. Pin | 19. Shaft |
| 5. Seal ring | 20. Joint |
| 6. Grease nipple | 21. Bushing |
| 7. Seal ring | 22. Brease nipple |
| 8. Seal ring | 23. Seal ring |
| 9. Bushing | 24. Cylinder head screw |
| 10. Axle tube | 25. Roller bearing |
| 11. Ring nut | 26. Washer |
| 12. Ball bearing | 27. Ring |
| 13. Ring nut | 28. Hexagon head screw |
| 14. Ball bearing | 29. Sun gear |
| 15. Seal ring | |

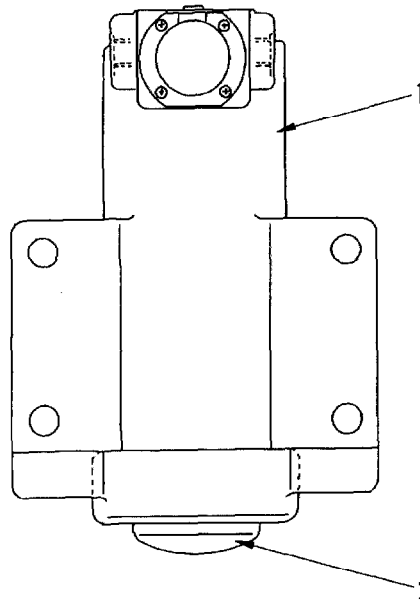
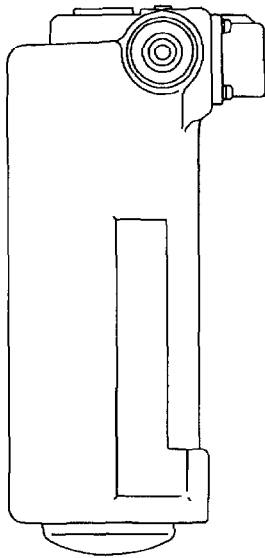
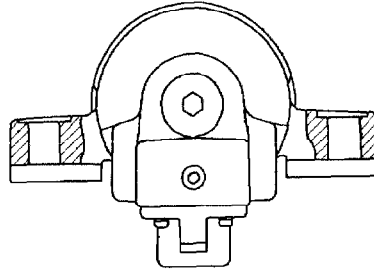
REAR AXLE



KW130P6008

- | | |
|----------------------|-------------------------|
| 1. Planetary gear | 16. Seal ring |
| 2. Bolt | 17. Roller bearing |
| 3. Planetary carrier | 18. Roller bearing |
| 4. Stud | 19. Bevel gear |
| 5. Wheel Hub | 20. Cylinder head screw |
| 6. Bushing | 21. Bearing |
| 7. Socket | 22. Ring gear plate |
| 8. Shaft | 23. Sun gear |
| 9. Axle tube | |
| 10. Ring nut | |
| 11. Roller bearing | |
| 12. Roller bearing | |
| 13. Shim | |
| 14. Bolt | |
| 15. Cover | |

SUSPENSION LOCK CYLINDER



KW130P6009

1. Barrel
2. Plunger

Specifications

Piston: $\varnothing 100\text{mm}$
Stroke: 155mm
Operating pressure: 40.0 MPa (408 Kg/cm²)
Pilot pressure: 3.0 MPa (30.6 Kg/cm²)
Max 5.0 MPa (51.0 Kg/cm²)

CIRCUIT

Purpose

The undercarriage of wheeled hydraulic excavators have one of the two driven axles oscillating mounted. This makes it possible to fully utilize the excavator's rimpull in rough terrain - all of the wheels being constantly in contact with the ground.

An oscillating blocking ram is fitted on each side of the undercarriage to block the axle during digging or lifting work.

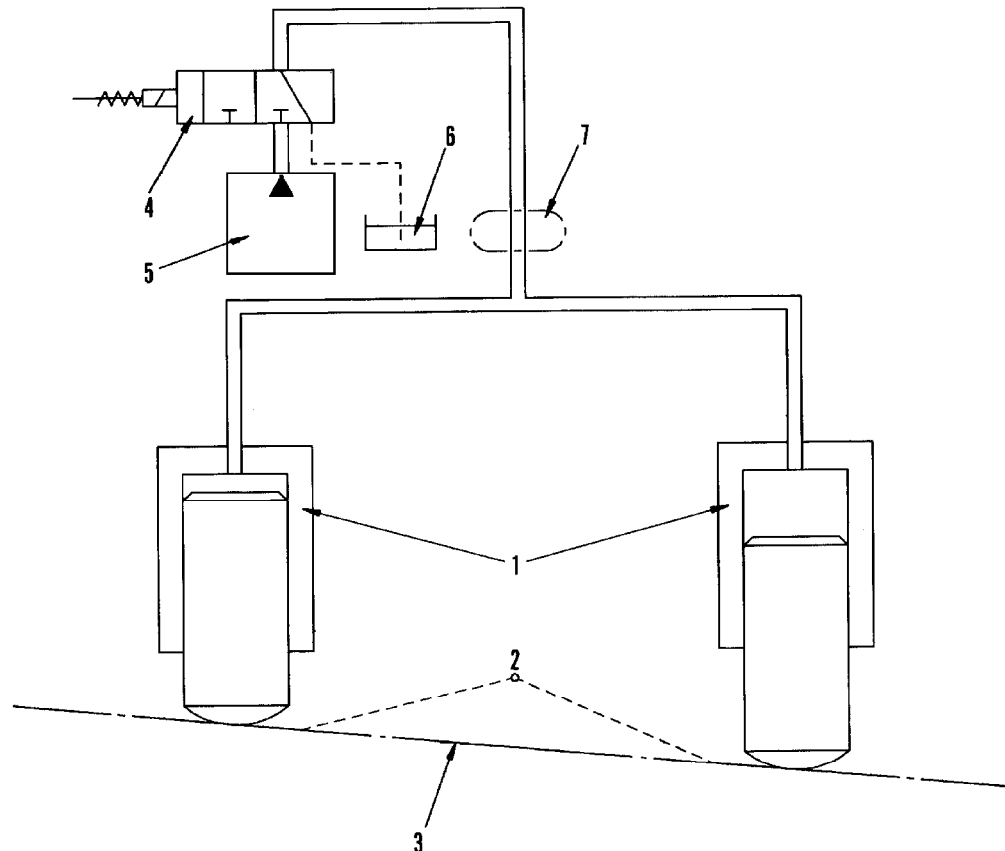
Blocking the axle increases the excavator's stability.

1. Ram
2. Axle oscillating point
3. Oscillating axle
4. Oscillation lock solenoid valve
5. PPC pressure reducing valve
6. Hydraulic tank
7. Swivel joint

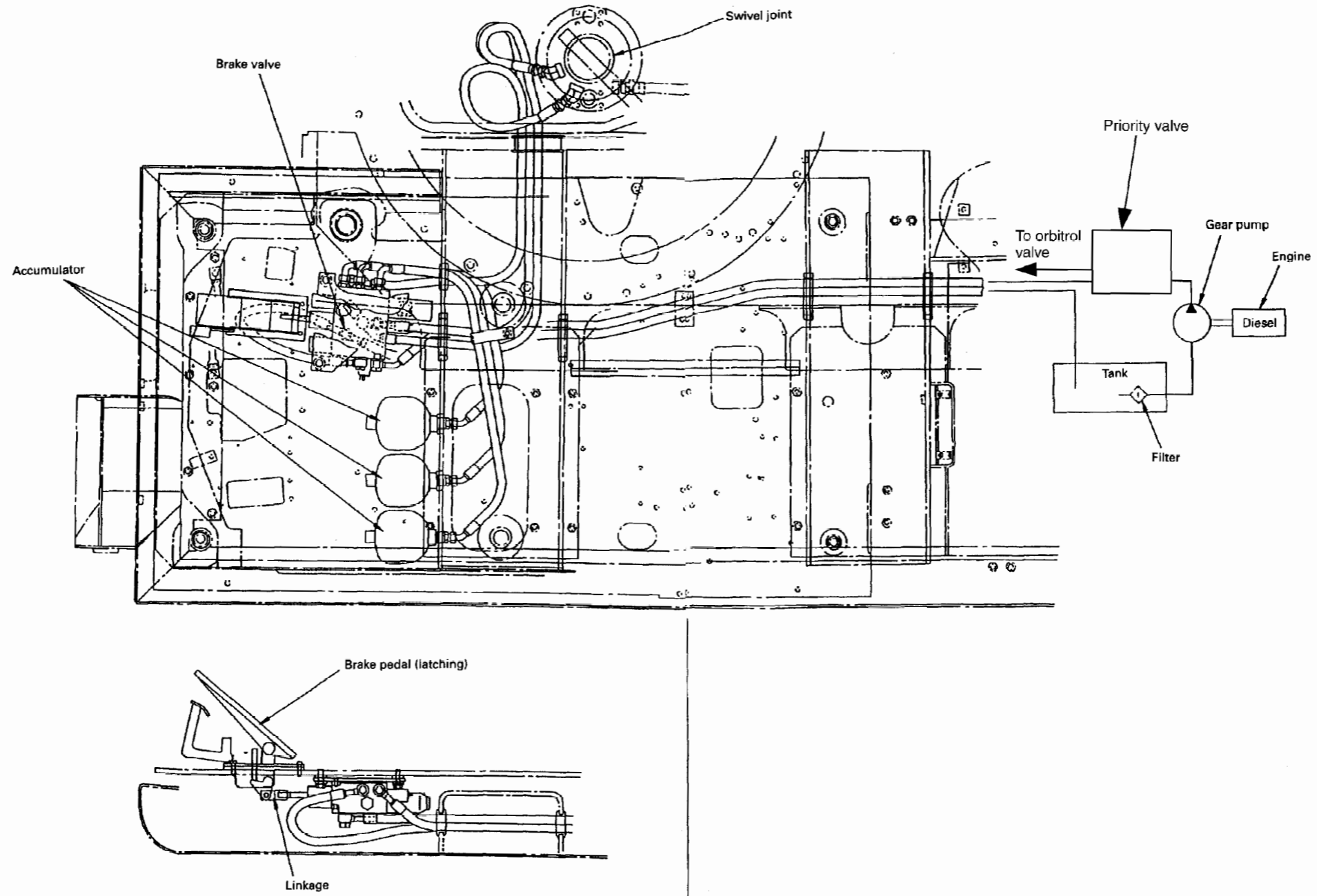
Function

The oscillating axle (3) is mounted in bearing (2) in the middle of the excavator. The two rams (1) which are full of hydraulic oil are connected through pipelines to the oscillation lock solenoid valve (4).

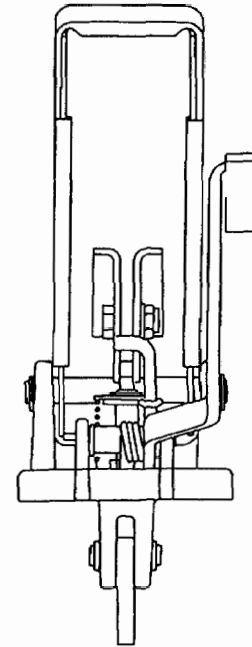
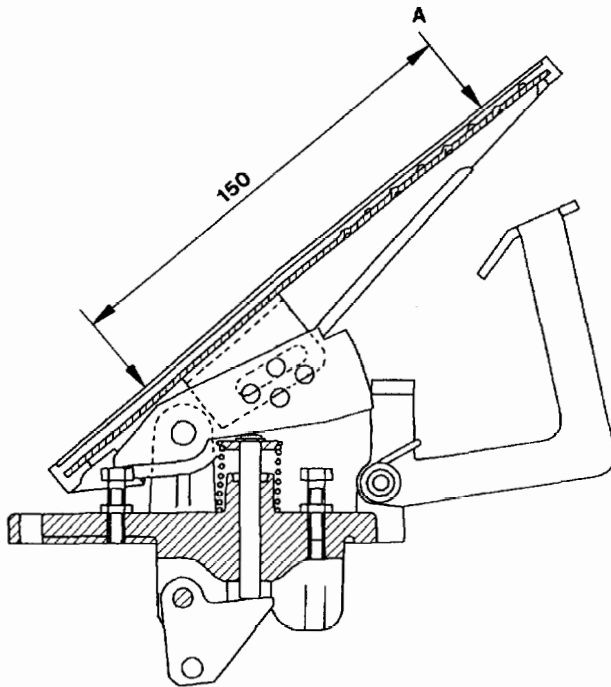
When the excavator is being moved, the oscillation lock solenoid valve should be de-energized so that the hydraulic oil in the ram can be returned to tank as the axle is oscillating up and down. Before commencing excavating operations, the oscillation lock solenoid valve should be energized to pressurize the oil in the rams. This will lock the axle in the position it is in.



BRAKING TRAIN



BRAKE PEDAL

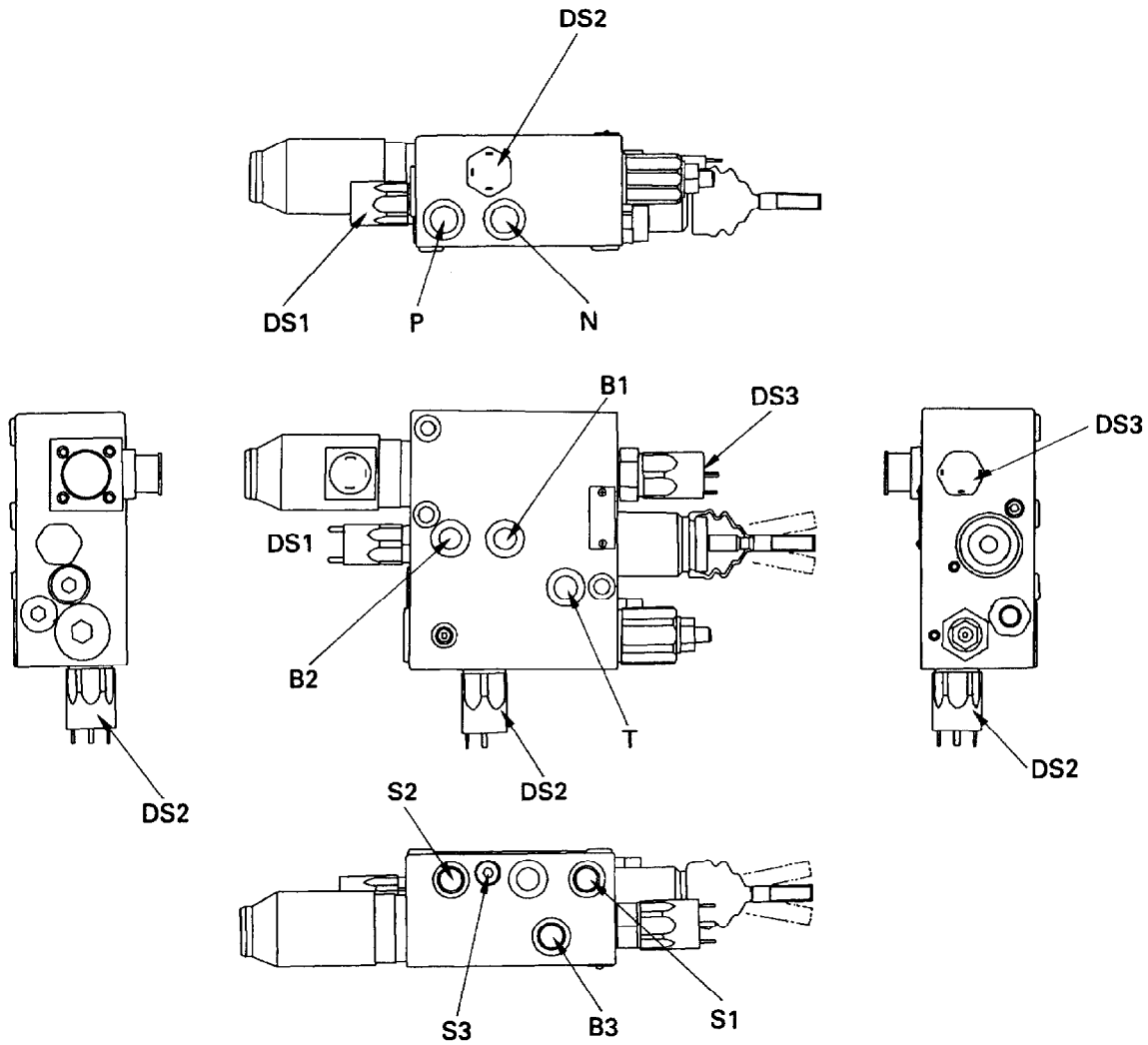


KW130P6012

Actuation force at 'A' = 300 - 350 N
(30.6 - 35.7 kg)

When installed in machine

BRAKE VALVE

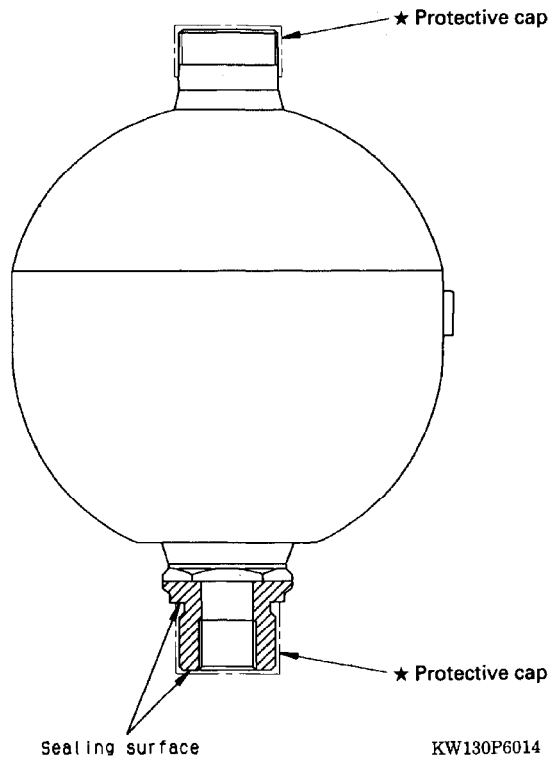


KW130P6013

P = Pump
 N = Secondary circuit
 T = Tank
 B1 = Service brake
 B2 = Service brake
 B3 = Parking brake

S1 = Accumulator service brake
 S2 = Accumulator service brake
 S3 = Accumulator parking brake
 DS1 = Pressure switch stop light
 DS2 = Pressure switch accumulator-pressure
 DS3 = Pressure switch parking brake

ACCUMULATOR FOR BRAKE SYSTEM



Specifications

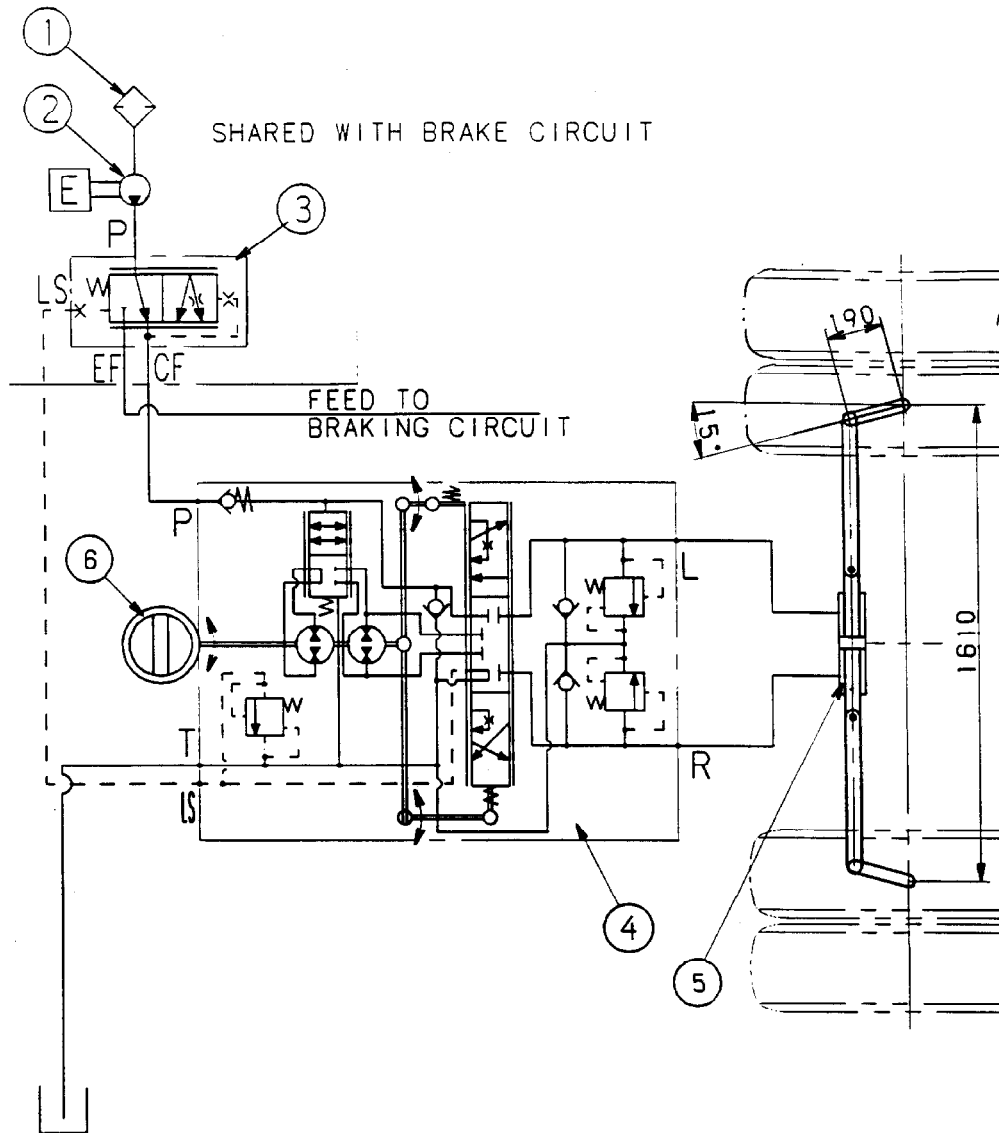
Volume: 0.75 ℓ

Max working pressure: 210 bar

Precharge pressure: 50 bar

* Remove before installation

STEERING TRAIN



STRUCTURE AND FUNCTION

- The steering is fully hydraulic. The oil sent by steering pump (2) mounted on the steering PTO at the front of the engine (1) flows to steering valve (4). From here is passed through swivel joint (6) and is sent to steering cylinder (7). The steering cylinder then extends or retracts to move tie-rod and steer the machine.
- The hydraulic power from steering pump (2) is sent to the steering cylinder and converted back to mechanical power to operate the steering.

ITEM POSITIONS

1. HYDRAULIC OIL FILTER
2. HYDRAULIC OIL PUMP (SHARED WITH BRAKING CIRCUIT) 18cc/REV
3. PRIORITY VALVE
CONTROL SPRING PRESSURE 7 bar
4. STEERING VALVE OSPD 70/195 LS DYN.
5. STEERING CILINDER D=Ø90, d=Ø50, STROKE=170,
STEERING CILINDER VOLUME = $\frac{(9-5) \times \pi}{4} \times 17 = 748 \text{ cm}^3$
6. STEERING WHEEL Ø352

QUANTITIY OF STEERING TURNS

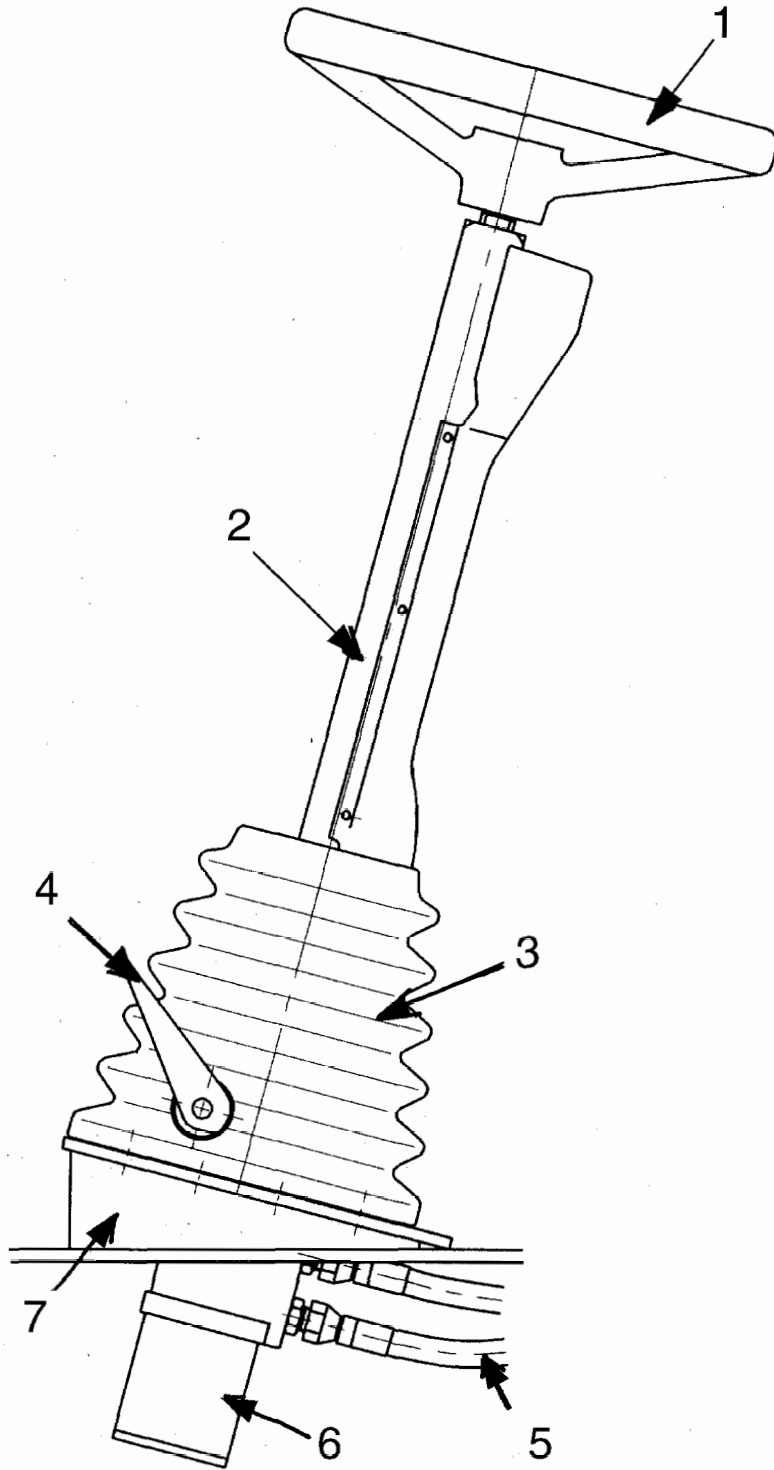
NORMAL

$$1 = \frac{\text{CYL.VOL}}{\text{PUMP.VOL}} = \frac{748 \text{ cm}^3}{195 \text{ cm}^3} = 3.8 \text{ TURNS}$$

EMERGENCY

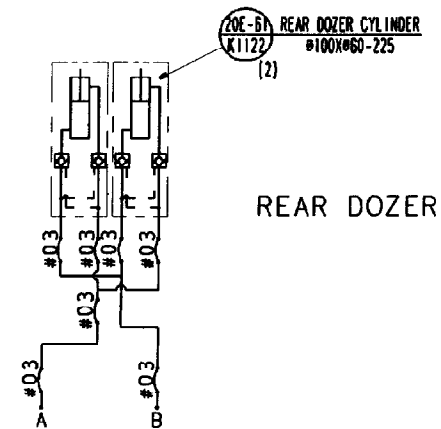
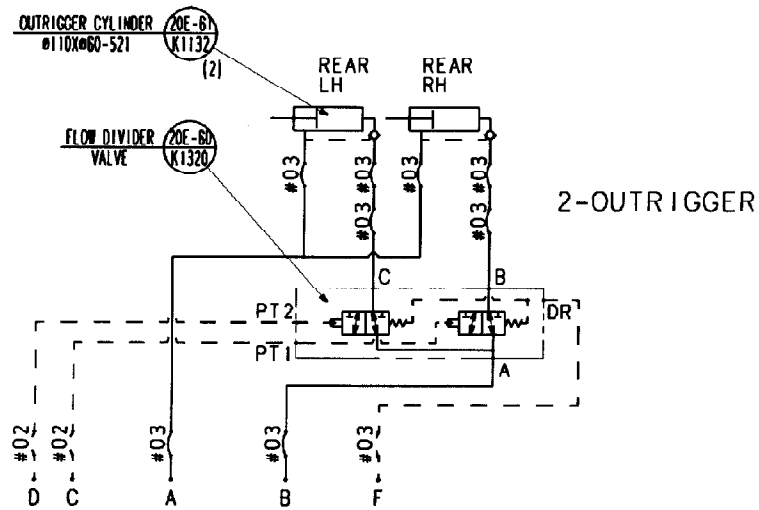
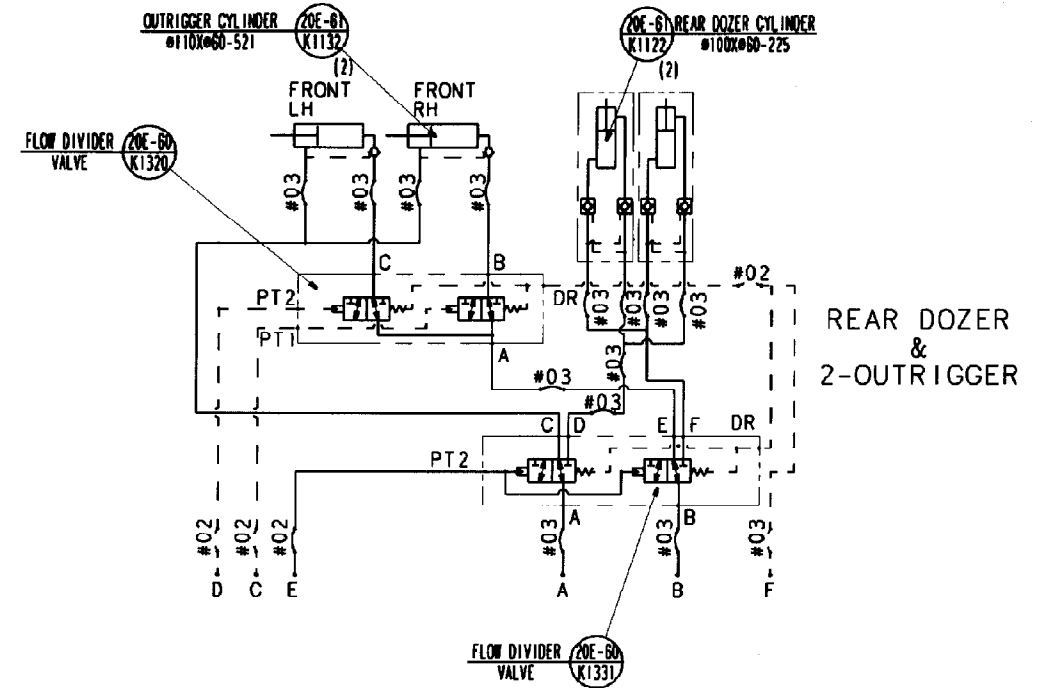
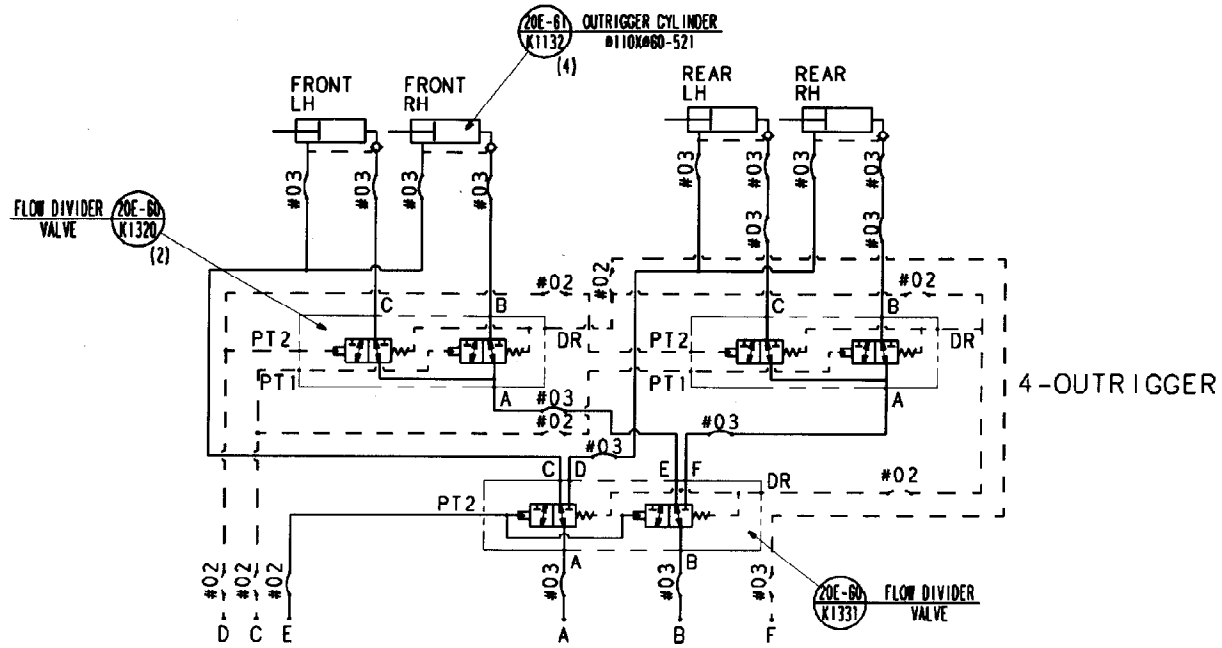
$$1 = \frac{\text{CYL.VOL}}{\text{PUMP.VOL}} = \frac{748 \text{ cm}^3}{70 \text{ cm}^3} = 10.7 \text{ TURNS}$$

STEERING COLUMN

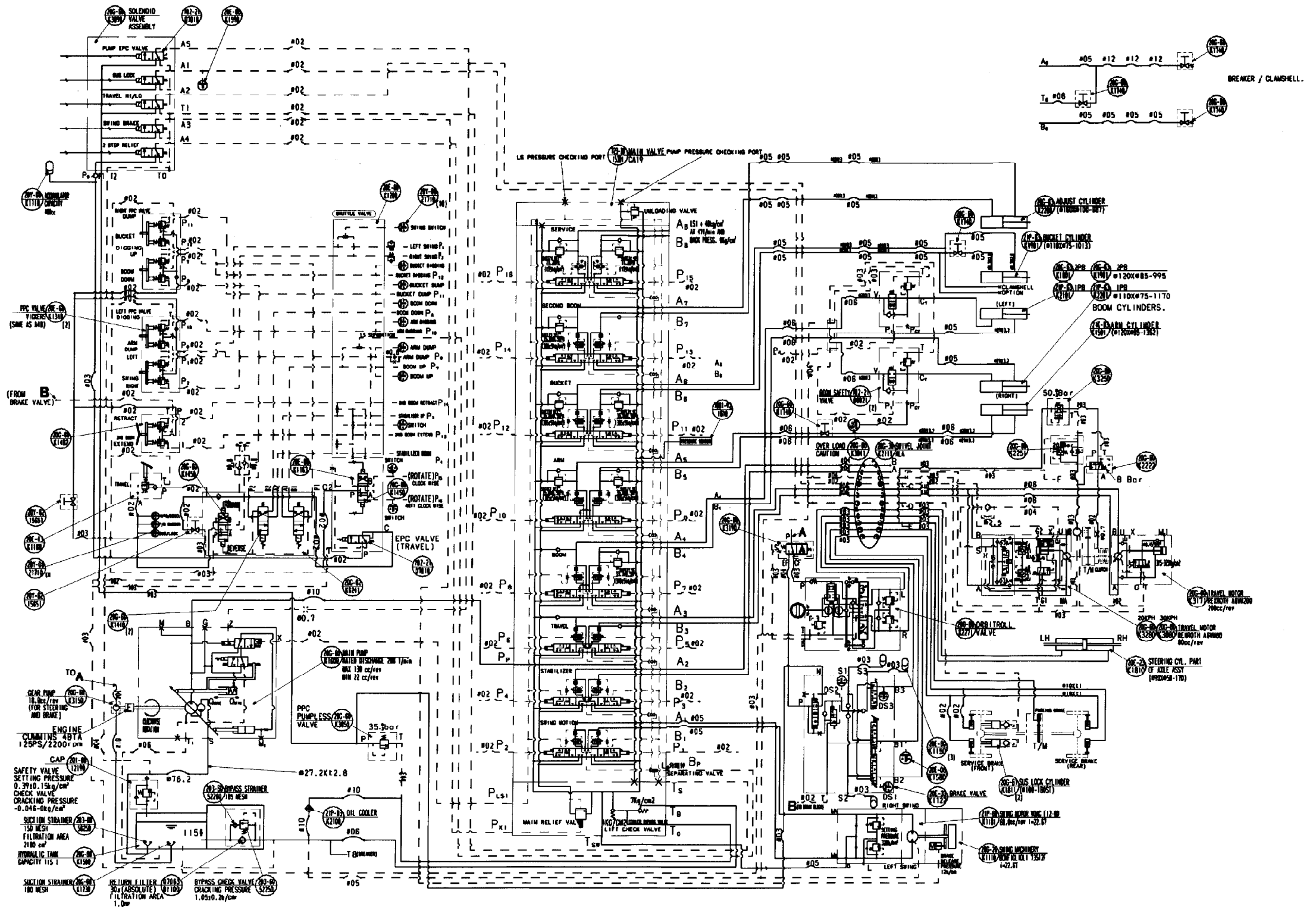


- 1. Steering wheel
- 2. Steering column
- 3. Gaiter
- 4. Pedal
- 5. Hose
- 6. Orbitroll valve
- 7. Mounting bracket

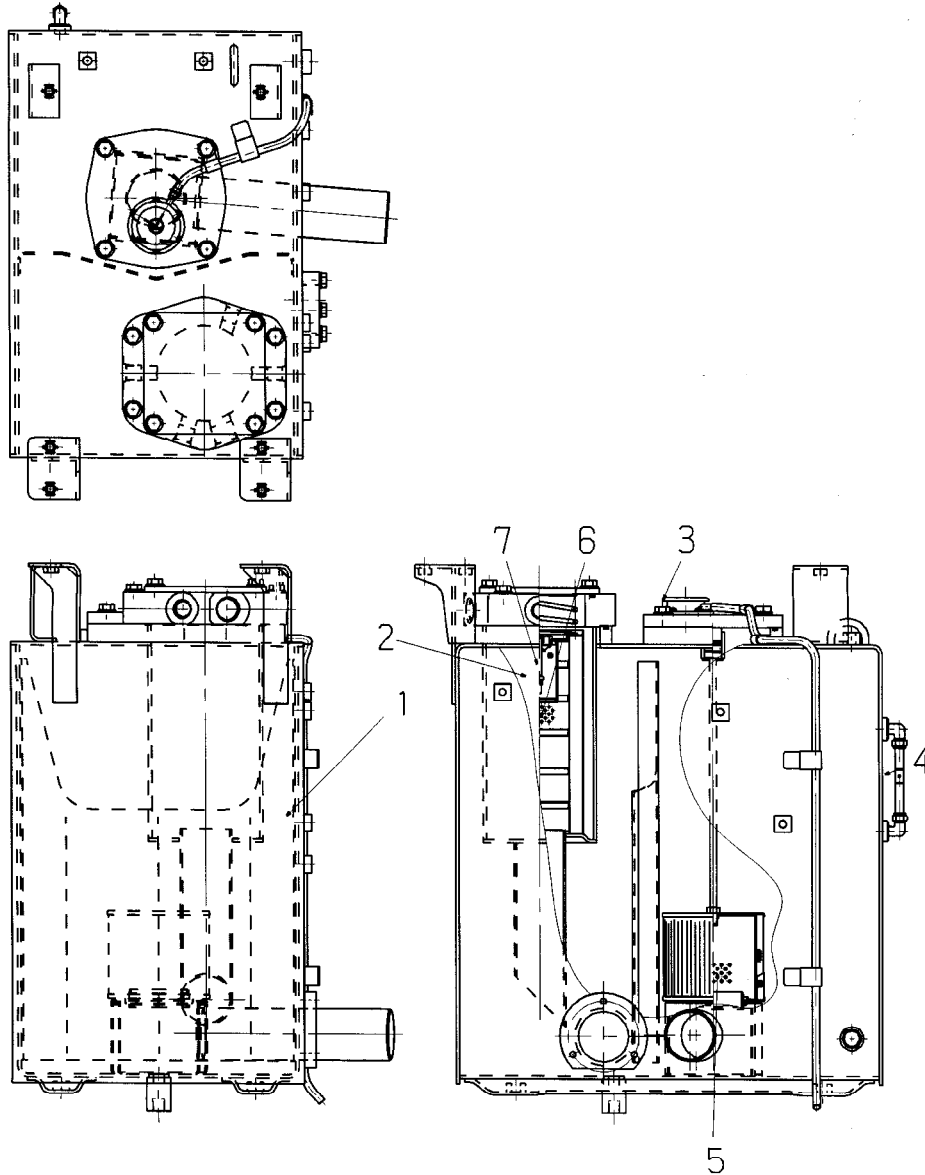
HYDRAULIC CIRCUIT DIAGRAM



HYDRAULIC CIRCUIT DIAGRAM



HYDRAULIC TANK



1. Hydraulic tank
2. Bypass valve
3. Oil filter cap
4. Sight gauge
5. Suction strainer
6. Filter element
7. Bypass strainer

Specifications

Tank capacity:

Amount of oil inside tank:

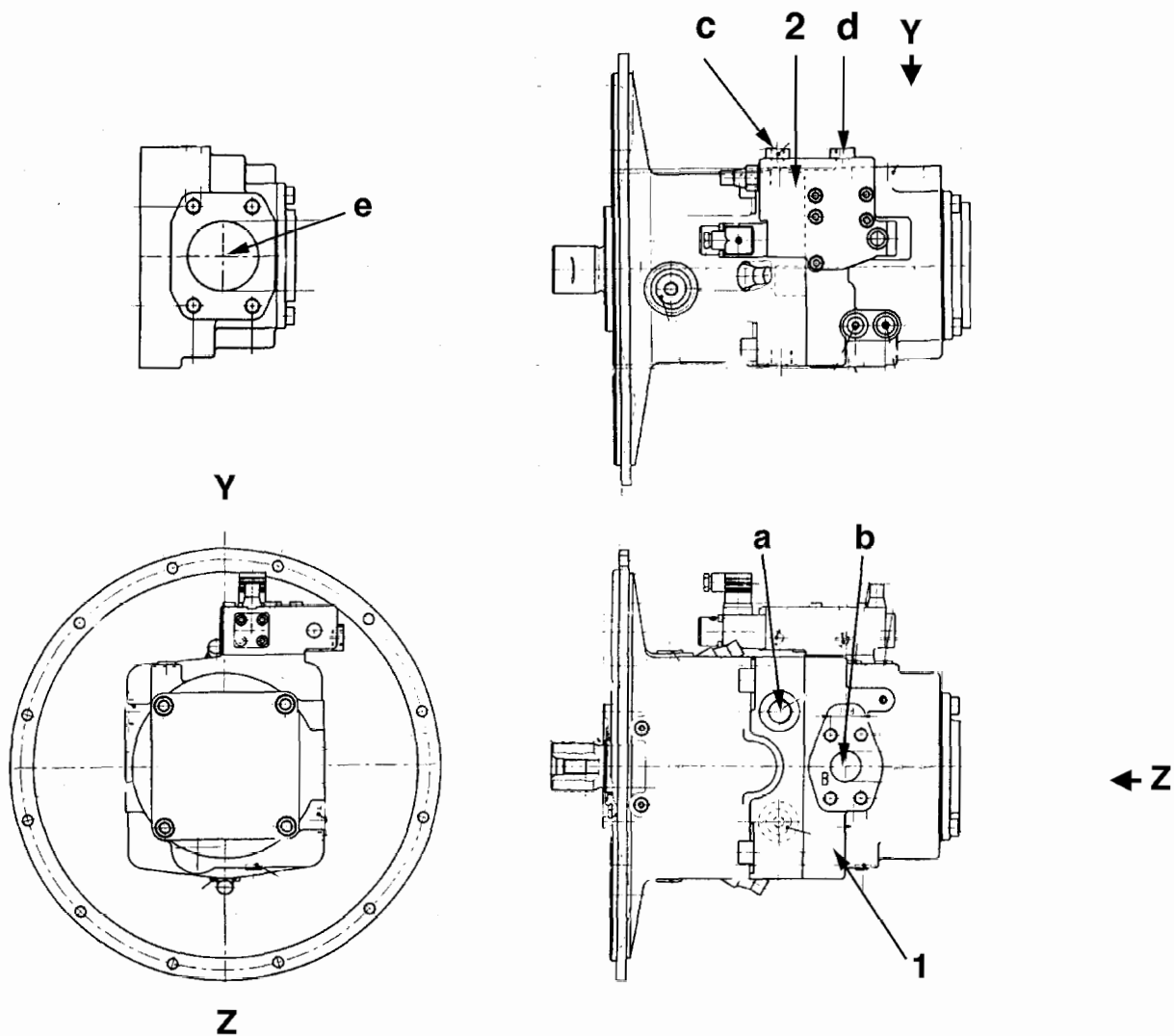
Pressure valve

Relief cracking pressure: 0.038 ± 0.015 MPa
 $(0.39 \pm 0.15 \text{ kg/cm}^2)$

Suction cracking pressure: $0 - 0.0045$ MPa
 $(0 - 0.046 \text{ kg/cm}^2)$

Bypass valve set pressure: 0.103 ± 0.02 MPa
 $(1.05 \pm 0.2 \text{ kg/cm}^2)$

HYDRAULIC PUMP



- a. Pump drain port **PD**
- b. Pump delivery port **PA**
- c. Pump LS pressure port **PLS**
- d. LS control EPC pressure port **PSIG**
- e. Main pump suction port **PS**

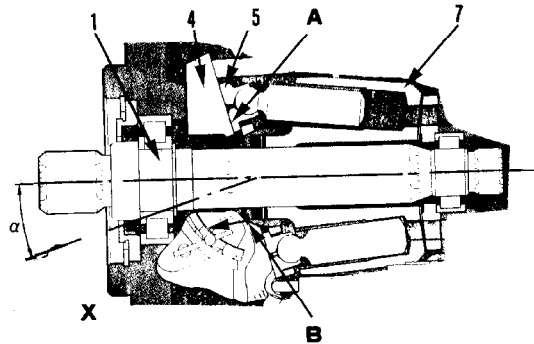
- 1. Main pump
- 2. TVC•LS valve

OPERATION

1. Operation of pump

- 1) cylinder block (7) rotates together with shaft (1), and shoe (5) slides on flat surface **A**.

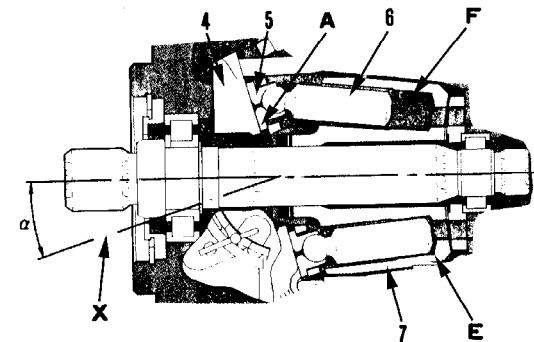
When this happens, rocker cam (4) moves along cylindrical surface **B**, so angle α between center line **X** of rocker cam (4) and the axial direction of cylinder block (7) changes. (Angle α is called the swash plate angle.)



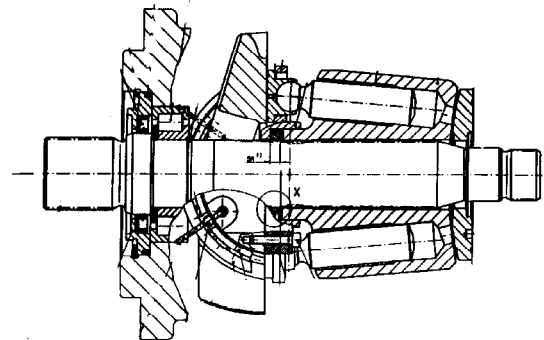
- 2) Center line **X** of rocker cam (4) maintains swash plate angle α in relation to the axial direction of cylinder block (7), and flat surface **A** moves as a cam in relation to shoe (5).

In this way, piston (6) slides on the inside of cylinder block (7), so a difference between volume **E** and **F** is created inside cylinder block (7). The suction and discharge is carried out by this difference **F** - **E**.

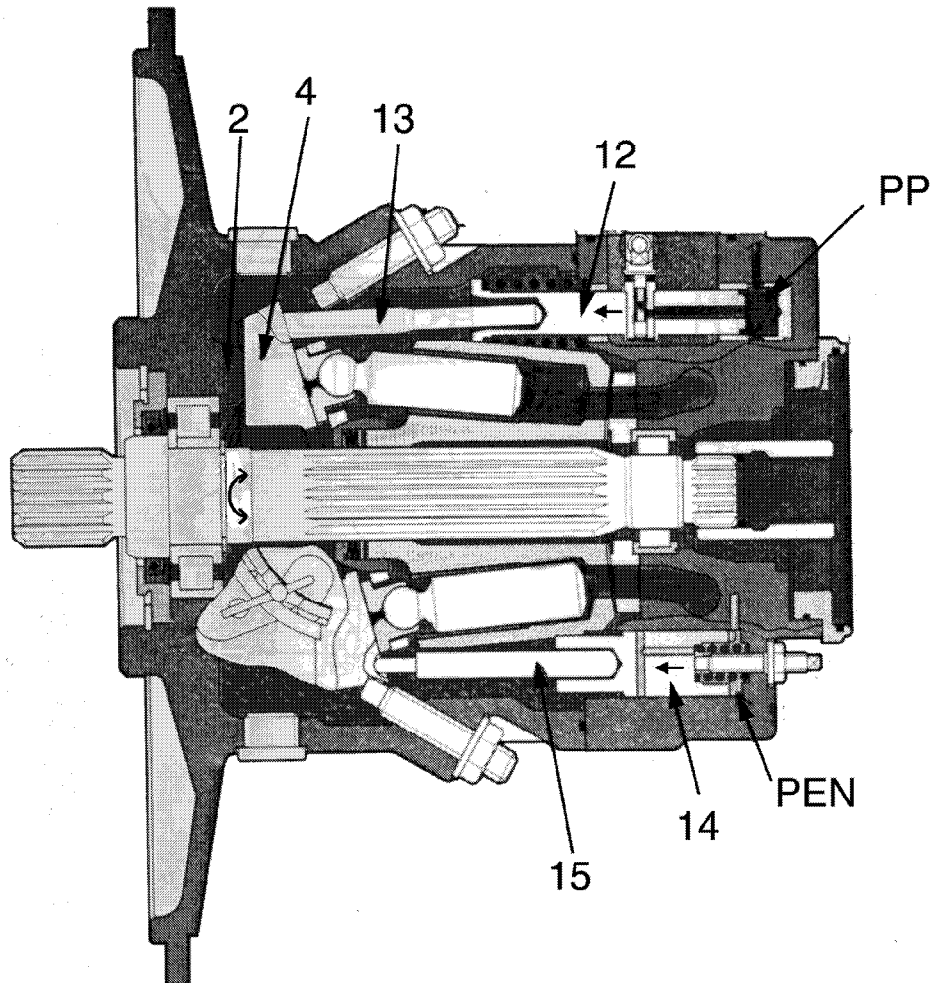
In other words, when cylinder block (7) rotates and the volume of chamber **E** becomes smaller, the oil is discharged during that stroke. On the other hand, the volume of chamber **F** becomes larger, and as the volume becomes bigger, the oil is sucked in.



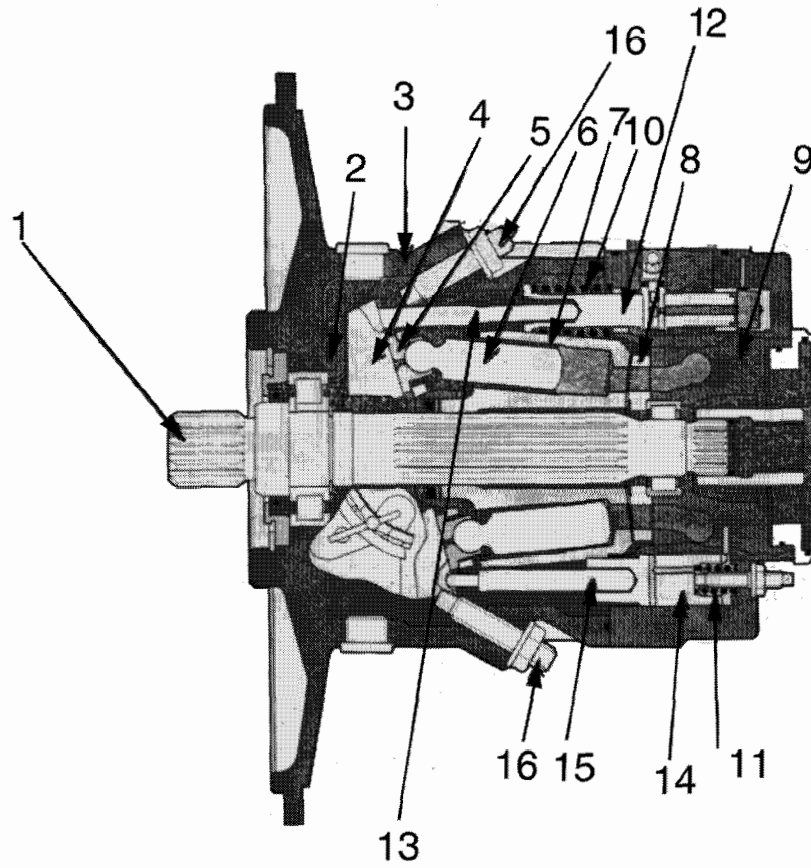
- 3) If center line **X** of rocker cam (4) is in line with the axial direction of cylinder block (7) (swash plate angle = 0), the difference between volumes **E'** and **F'** inside cylinder block (7) becomes 0, so the pump does not carry out any suction or discharge of oil. (In actual fact, the swash plate angle never becomes 0.)



2. CONTROL OF DISCHARGE AMOUNT

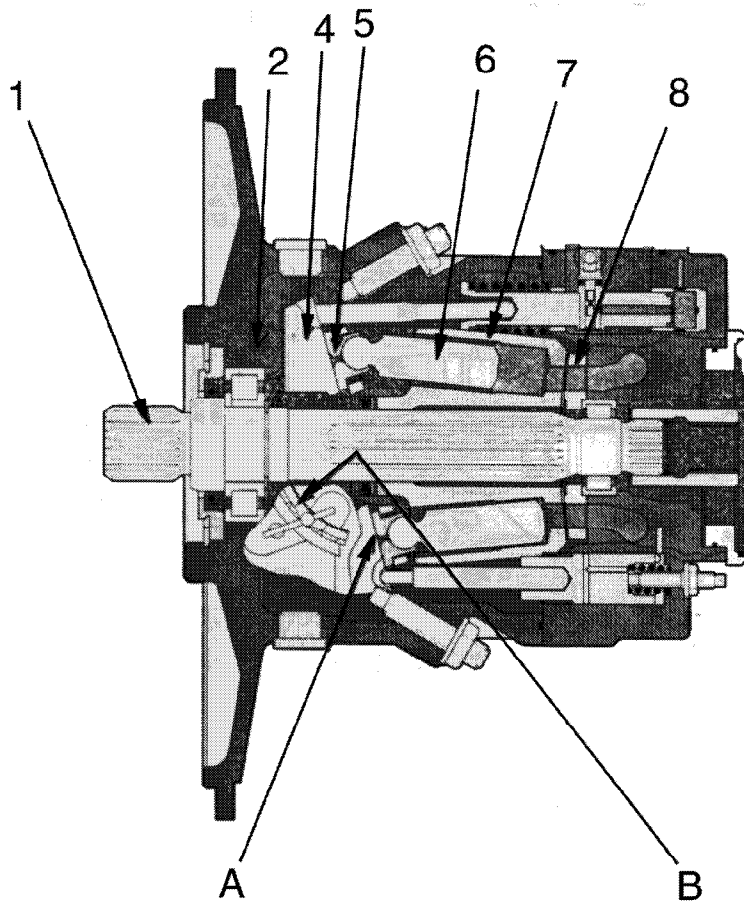


- If swash plate angle α becomes larger, the difference in volumes **E** and **F** becomes larger and discharge volume **Q** increases.
- Swash plate angle α is changed by positioning piston (12) and return piston (14).
- Servo piston (12) moves in a reciprocal movement (\longleftrightarrow) according to the spring force and pump output pressure.
- This straight line movement is transmitted through rod (13) and (15) to rocker cam (4), and rocker cam (4), which is supported by the cylindrical surface to cradle (2), moves in a swinging movement on the cylindrical surface in (direction).
- Piston (14) moves in a reciprocal movement (\longleftrightarrow) according to the command from the TVC•LS valve and the spring force.
- Main pump discharge pressure (self-pressure) **PP** is always connected to the chamber receiving the pressure on piston (12) end. (the self-pressure is brought in).
- Output pressure **PEN** of the LS valve is brought to the chamber receiving the pressure at piston (14) end.
- The relationship between piston (12) and piston (14) controls swash plate (4) angle.



- 1. Shaft
- 2. Cradle
- 3. Case
- 4. Rocker cam
- 5. Shoe
- 6. Piston
- 7. Cylinder block
- 8. Valve plate

- 9. End cap
- 10. Spring
- 11. Spring
- 12. Positioning piston
- 13. Rod
- 14. Return piston
- 15. Rod
- 16. Stopper



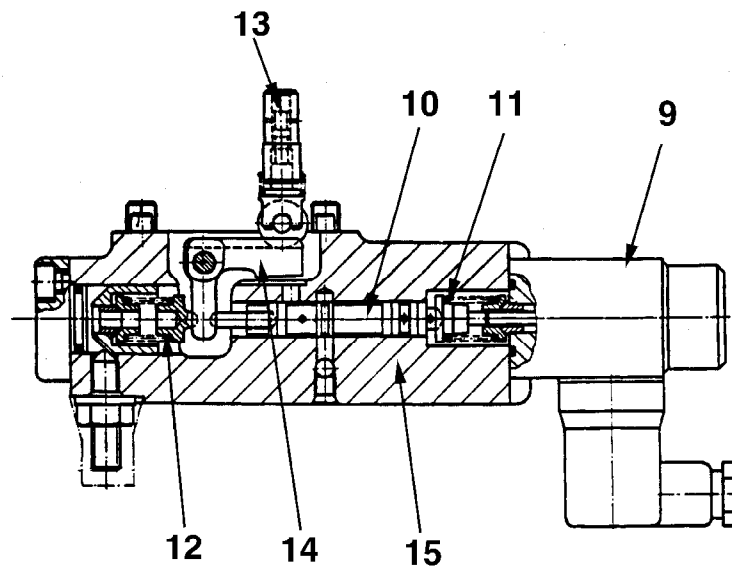
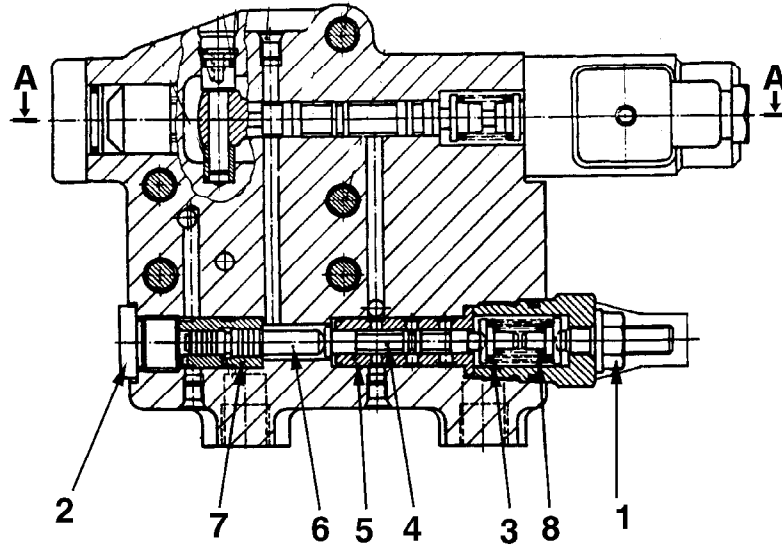
FUNCTION

- The engine rotation and torque transmitted to the pump shaft is converted into hydraulic energy, and pressurized oil is discharged according to the load.
- It is possible to change the delivery amount by changing the swash plate angle.

STRUCTURE

- Cylinder block (7) is supported to shaft (1) by a spline, and shaft (1) is supported by the front and rear bearings.
- The tip of piston (6) is a convex ball, and shoe (5) is caulked to it to form one unit. Piston (6) and shoe (5) form a spherical bearing.
- Rocker cam (4) has flat surface **A**, and shoe (5) is always pressed against this surface while sliding in a circular movement.
- Rocker cam (4) brings high pressure oil at cylindrical surface **B** with cradle (2), which is secured to the case, and forms a static pressure bearing when it slides.
- Piston (6) carries out relative movement in the axial direction inside each cylinder chamber of cylinder block (7).
- The cylinder block seals the pressure oil to valve plate (8) and carries out relative rotation. This surface is designed so that the oil pressure balance is maintained at a suitable level. The oil inside each cylinder chamber of cylinder block (7) is sucked in and discharged through valve plate (8).

2. TVC. LS valve



LS VALVE

- 1. Locknut
- 2. Plug
- 3. Spring
- 4. Spool
- 5. Sleeve
- 6. Piston
- 7. Sleeve
- 8. Spring

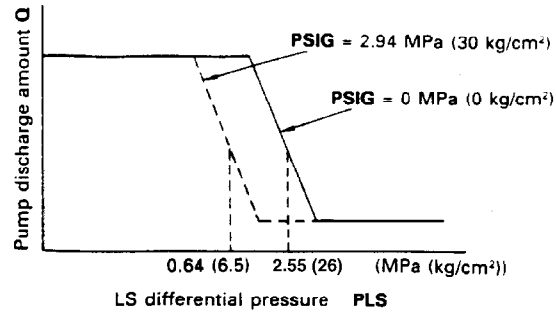
TVC VALVE

- 9. Solenoid
- 10. Piston
- 11. Spring
- 12. Spring
- 13. Piston
- 14. Lever
- 15. Valve body

FUNCTION

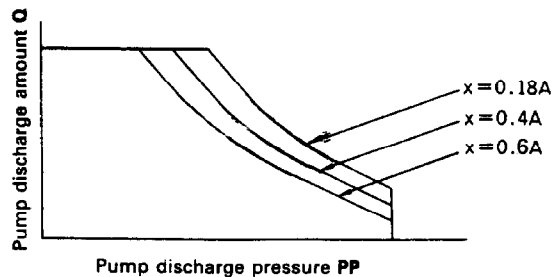
1. LS VALVE

- The **LS** valve detects the load and controls the discharge amount.
This valve controls main pump discharge amount **Q** according to differential pressure ΔPLS ($=\text{PP} - \text{PLS}$) (the difference between main pump pressure **PP** and control valve outlet port pressure **PLS**) (called the **LS** differential pressure).
- Main pump pressure **PP**, pressure **PLS** (called the **LS** pressure) coming from the control valve output, and pressure **PSIG** (called the **LS** selection pressure) from the proportional solenoid valve enter this valve. The relationship between discharge amount **Q** and differential pressure ΔPLS , (the difference between main pump pressure **PP** and **LS** pressure **PLS**) ($=\text{PP} - \text{PLS}$) changes as shown in the diagram on the right according to **LS** selector pressure **PSIG**.
- When **PSIG** changes between 0 and 2.94 MPa (0 and 30 kg/cm²), the spool load changes according to this, and the selector point for the pump discharge amount changes at the rated central value between 0.64 and 2.55 MPa (6.5 and 26 kg/cm²).



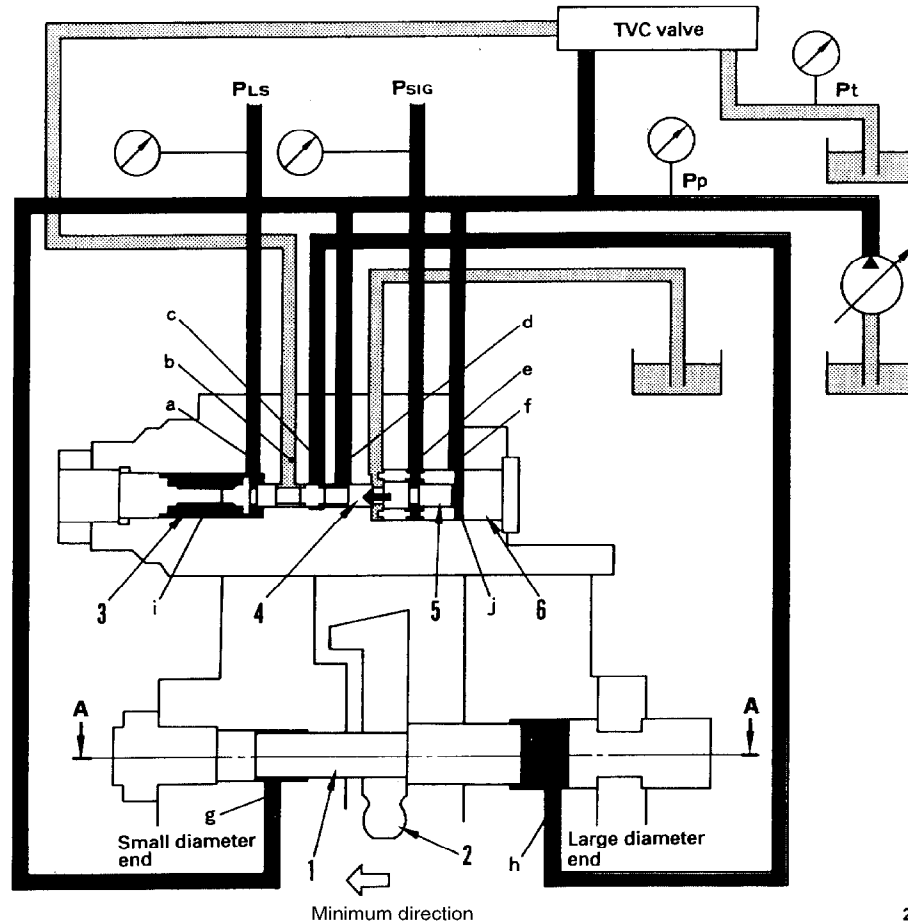
2. TVC VALVE

- When the pump discharge pressure **PP** (selfpressure) is high, the TVC valve controls the pump so that no more oil than the constant flow (in accordance with the discharge pressure) flows even if the stroke of the control valve becomes larger. In this way it carries out equal horsepower control so that the horsepower absorbed by the pump does not exceed the engine horsepower.
- In other words, if the load during the operation becomes larger and the pump discharge pressure rises, it reduces the discharge amount from the pump; and if the pump discharge pressure drops, it increases the discharge amount from the pump. The relation between the pump discharge pressure **PP** and pump discharge amount **Q** is shown on the right, with the current given to the TVC valve solenoid shown as a parameter. However, in the heavy-duty operation mode, there are cases where it is given the function of sensing the actual speed of the engine, and if the speed drops because of an increase in the load, it reduces the pump discharge amount to allow the speed to recover. In other words, when the load increases and the engine drops below the set value, the command



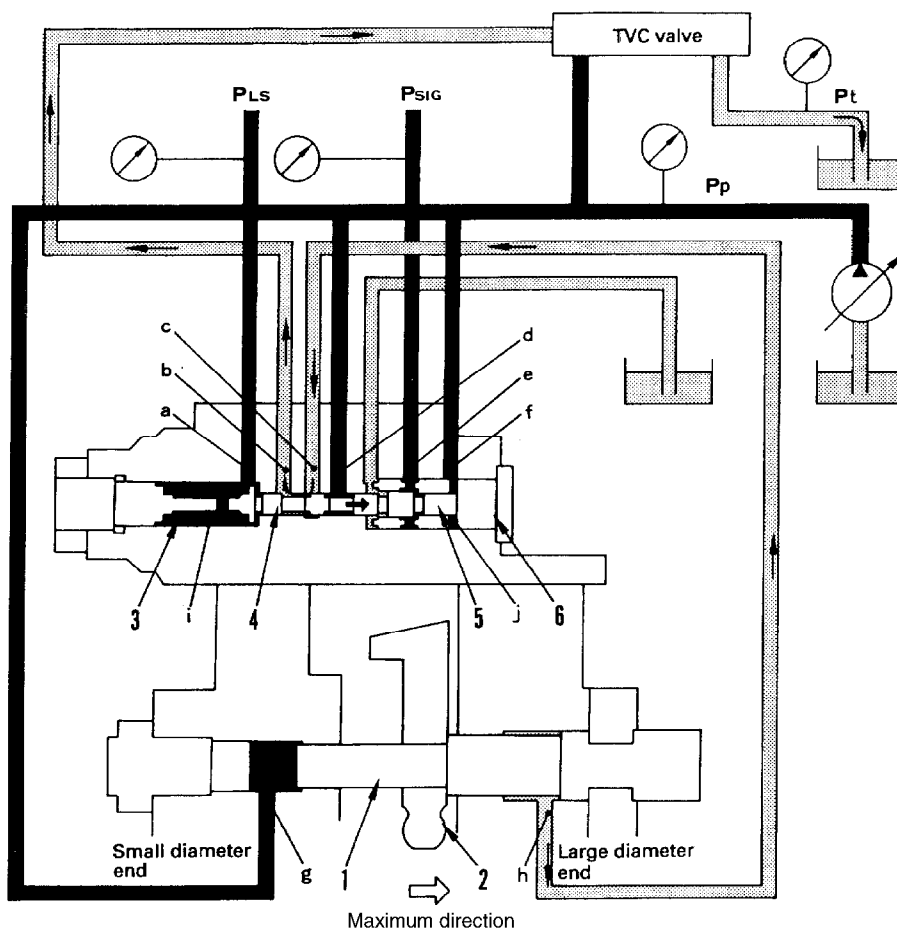
to the TVC valve solenoid from the controller increases according to the drop in the engine speed to reduce the pump swash plate angle.

OPERATION



1. **LS valve**
- 1) **When control valve is at "NEUTRAL" position**
 - The LS valve is a three-way selector valve, with pressure **PLs** (LS pressure) from the outlet port of the control valve brought to spring chamber i, and main pump discharge pressure **PP** brought to chamber j of plug (6). The size of this LS pressure **PLs** + force **F** of spring (3) and the main pump pressure (self pressure) **Pp** determines the position of spool (4). However, the size of the output pressure **Psig** (the LS selection pressure) of the EPC valve for the LS valve entering port e also changes the position of spool (4). (The set pressure of the spring changes.)
 - Before the engine is started, servo piston (1) is pushed to the right by spring (7) installed to rod (2). (See the diagram on the right.)
 - When the engine is started and the control lever is at the "NEUTRAL" position, LS pressure **PLs** is 0 MPa (0 kg/cm²). (It is interconnected with the drain circuit through the control valve spool.) At

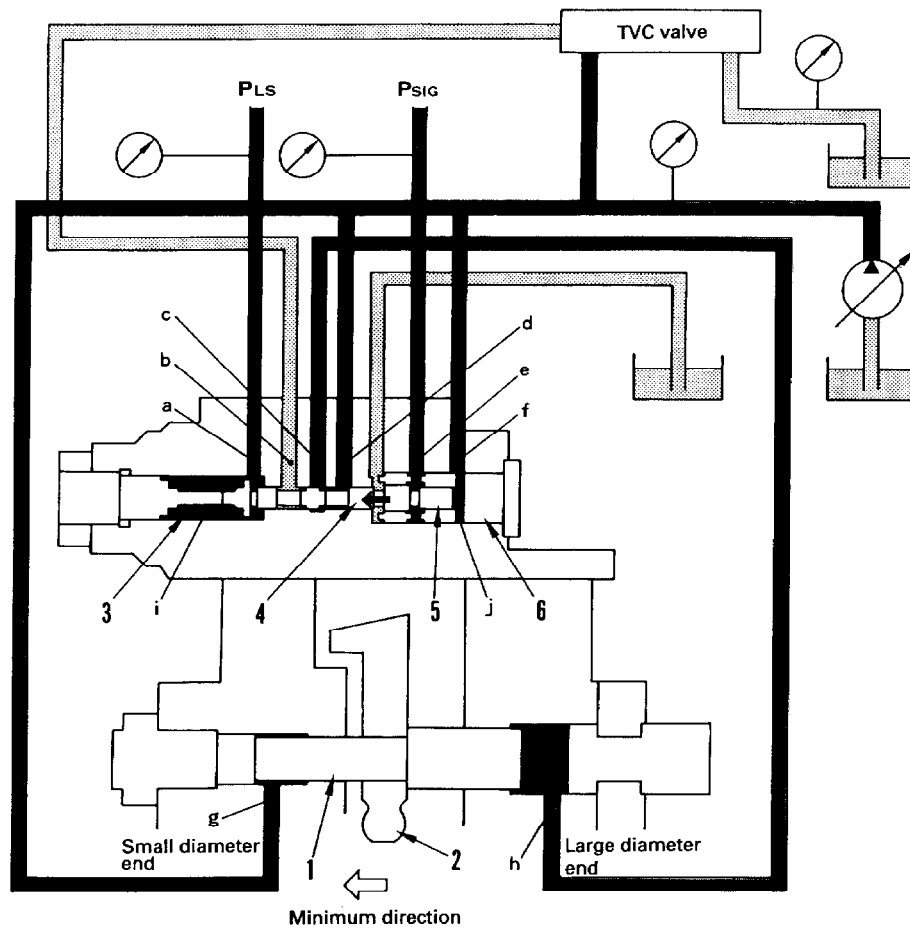
this point, spool (4) is pushed to the left, and port d and port C are connected. Pump pressure **Pp** enters the large diameter end of the piston from port h, and the same pump pressure **Pp** also enters the small diameter end of the piston, so the swash plate is moved to the minimum angle by the difference in area of piston (1).



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2) Operation in maximum direction for pump discharge amount

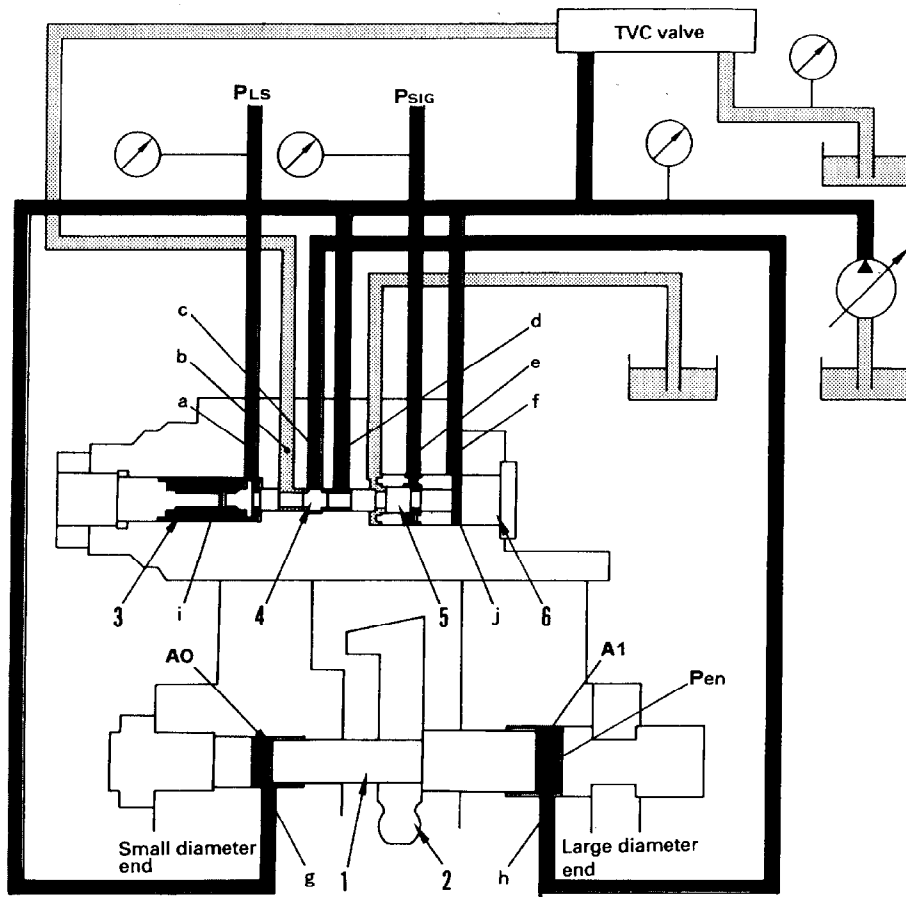
- When the difference between main pump pressure P_p and LS pressure PL_s , in other words, LS differential pressure PL_s , becomes smaller (for example, when the area of opening of the control valve becomes larger and pump pressure P_p drops), spool (4) is pushed to the right by the combined force of LS pressure PL_s and the force of spring (3).
- When spool (4) moves, port **b** and port **c** are joined and connected to the TVC valve. When this happens, the TVC valve is connected to the drain port, so circuit **c - h** becomes drain pressure P_t . (The operation of the TVC valve is explained later.)
- For this reason, the pressure at the large piston diameter end of servo piston (1) becomes drain pressure P_t , and pump pressure P_p enters the small diameter end, so servo piston (1) is pushed to the right. Therefore, rod (2) moves to the right and moves the swash plate in the direction to make the discharge amount larger.
- If the output pressure of the EPC valve for the LS valve enters port **e**, this pressure creates a force to move piston (5) to the left. If piston (5) is pushed to the left, it acts to make the set pressure of spring (3) weaker, and the difference between PL_s and P_p changes when ports **b** and **c** of spool (4) are connected.



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3) Operation in minimum direction for pump discharge amount

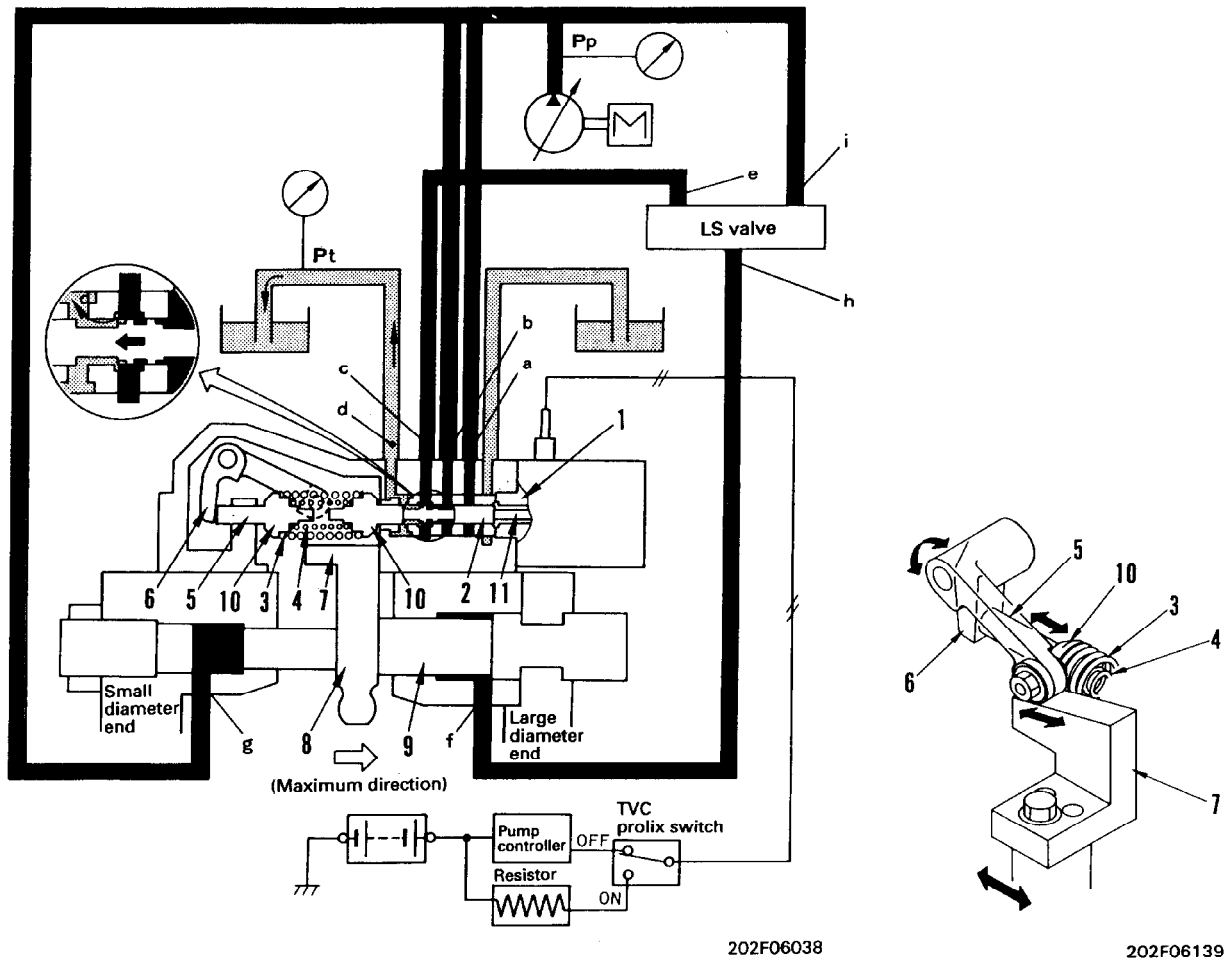
- The following explains the situation if servo piston (1) moves to the left (the discharge amount becomes smaller). When LS pressure ΔP_{LS} becomes larger (for example, when the area of opening of the control valve becomes smaller and pump pressure P_p rises), pump pressure P_p pushes spool (4) to the left.
- When spool (4) moves, main pump pressure P_p flows from port **d** to port **c**, and from port **h**, it enters the large piston diameter end.
- Main pump pressure P_p also enters the small piston diameter end, but because of the difference in area between the large piston diameter end of servo piston (1) and the small piston diameter end of servo piston (1) is pushed to the left. As a result, rod (2) moves in the direction to make the swash plate angle smaller.
- If LS selection pressure P_{sig} enters port **e**, it acts to make the set pressure of spring (3) weaker.



202F06037

4) When servo piston is balanced

- Let us take the area receiving the pressure at the large piston diameter end as **A1**, the area receiving the pressure at the small diameter end as **A0**, and the pressure flowing into the large piston diameter end as **Pen**. If the main pump pressure **Pp** of the LS valve and the combined force of force **F** of spring (3) and LS pressure **PLs** are balanced, and the relationship is **A0 x Pp = A1 x Pen**, servo piston (1) will stop in that position, and the swash plate will be kept at an intermediate position. (It will stop at a position where the opening from port **b** to port **c** and from port **d** to port **c** of spool (4) is approximately the same.)
- At this point, the relationship between the area receiving the pressure at both ends of piston (1) is **A0:A1 = 1:2**, so the pressure applied to both ends of the piston when it is balanced becomes **Pp: Pen = 2:1**.
- The position where spool (4) is balanced and stopped is the standard center, and the force of spring (3) is adjusted so that it is determined when **Pp - PLs = 2.11 MPa (21.5 kg/cm²)**. However, if **Psig** (the output pressure of 0 - 2.94 MPa (0 - 30 kg/cm²) of the EPC valve of the LS valve) is applied to port **e**, the balance stop position will change in proportion to pressure **Psig** between **Pp - PLs = 2.11 ↔ 0.637 MPa (21.5 ↔ 6.5 kg/cm²)**.



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2. TVC valve

1) When pump controller is normal

a. When the load on the actuator is small and pump pressure Pp is low

- (1) Movement of solenoid (1)
 - The command current from the pump controller flows to solenoid (1). This command current changes the internal force pushing solenoid push pin (11).
 - On the opposite site to the force pushing this solenoid push pin (11) is the spring set pressure of springs (3) and (4) and pump pressure Pp. Piston (2) stops at a position where the combined force pushing piston (2) is balanced, and the pressure (pressure of port c) output from the TVC valve changes according to this piston.

- The size of command current X is determined by the nature of the operation (lever operation), the selection of the working mode, and the set value and actual value for the engine speed.

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